

KALIMER-600 PDRC
Development of Quantification Method for design parameters of
PDRC system in KALIMER-600

150

가 150 MWe KALIMER
 600 MWe 가 KALIMER-600
 가 1589.3 MWth KALIMER-600
 가
 (Passive Decay heat Removal Circuit ; PDRC)
 (PDRC)
 KALIMER-600
 KALIMER-600 PDRC
 PDRC (design point)
 UA

Abstract

The conceptual design of a sodium cooled liquid metal reactor, KALIMER (Korea Advanced Liquid Metal Reactor) of which electric output is 150 MWe, has performed by KAERI (Korea Atomic Energy Research Institute). A revised design concept up-rating electric capacity to 600 MWe, named as KALIMER-600, has been currently developed. The residual heat removal (RHR) system under a loss of normal heat sink accident of KALIMER-600 is characterized by the concept of PDRC (Passive Decay heat Removal Circuit) and it has superiority in the aspect that an enough decay heat removal capacity can be provided since it uses a very simple concept of direct reactor pool cooling. This study describes quantification method for the steady-state design parameters of PDRC system at the design point. On the basis of the inter-relationship between the various design parameters quantified by using the method, overall characteristics of PDRC system corresponding to the variations of system design parameters have been investigated, and more detail calculations are also performed using the quantified results such as the variations of the temperature, pressure loss, mass flow rate and UA values in each heat transfer circuit and heat exchangers in PDRC system.

1.

(pool)

, 1,000MWth
(RVACS)

[1]. 1589.3MWth KALIMER-600 ,
가

가 가 72 grace time
(active component)

PDCR (Passive safety-grade Decay heat Removal Circuit)

KALIMER-600 KALIMER-600
PDCR (design point) PDCR
UA PDCR
가

2. KALIMER-600 PDCR

2.1 PDCR

PDCR 1 (pool) -
(DHX) - (AHX)

[2]. SPX (Super Phenix)
EFR (European Fast Reactor) [3][4]

[3][4]
[2]. PDCR 2
600MWe KALIMER-600 가 , 1
(DHX) - (AHX) . , 1
DHX (AHX)
가
1 DHX / DHX
(DHX support barrel) PHTS
(head) /
. DHX (DHX support barrel) (baffle) over

flow slot PHTS
 , 가 DHX
 KALIMER-150 PSDRS[5]
 DHX (DHX support barrel)
 PHTS DHX shell , DHX
 (DHX support barrel) / 가
 가 DHX shell 가
 DHX 가 , DHX
 (closed loop or system)
 2 AHX DHX
 가 (AHX)
 DHX (DHX support barrel) - (DHX)
 PHTS
 (pool) DHX (DHX support barrel)
 DHX 2
 , [3][4]

2.2 PDRC

KALIMER-600 PDRC
 가, , PDRC
 (design point) , PDRC (design point)
 PDRC ,
 , KALIMER-600
 (design point) KALIMER-150 [5]
 , 392.2MWth KALIMER-150 ,
 2 17 ,
 (design point) 2.6 MWth ,
 , (design point) 10~20
 (pool)

(thermal inertia)
 (design point) . 3 1589.3MWth KALIMER-600
 , (design
 point) 10~20 , PDRC
 10~12 MWth , (design point)
 , KALIMER-
 600 PDRC 가 (design point)
 가 10
 KALIMER-600 , 10
 12.09MWth 6.05 MWth가
 PDRC (design point)
 PDRC

2.3 PDRC

PDRC “ (pool) – DHX shell – DHX
 tube – AHX – ”
 PDRC PDRC

$$\frac{Q_{PDRC}}{\dot{m}_p} = \frac{T_{PH} - T_{PC}}{T_{LH} - T_{LC}} \frac{\{UA\}_{DHX}}{\{UA\}_{AHX}} \frac{T_{AH} - T_{AC}}{\dot{m}_a}$$
 DHX AHX KALIMER-600 PDRC 가
 T_{PH} T_{AC} ,
 가 PDRC
 가 , DHX
 PDRC 가
 , DHX [6]
 DHX
 547.86°C , DHX
 shell 가
 KALIMER-150[5] 40°C

3. PDRC

3.1

KALIMER-600 PDRC

3 , PDRC

PHTS 1 가 - (DHX)

(AHX)

가

PDRC

5 5

(40°C) PHTS

DHX

shell

DHX 가

, 3 가

3

UA , 5 (T_{PC}, T_{LH},

T_{LC}, T_{AH}) 3

(UA_{DHX}, UA_{AHX})

PDRC

(design point)

$$Q_{DHX}^{rej} = \{UA\}_{DHX} \cdot \Delta T_{LMTD}(T_{PH}, T_{PC}, T_{LH}, T_{LC}) \quad (1)$$

$$Q_{AHX}^{rej} = \{UA\}_{AHX} \cdot \Delta T_{LMTD}(T_{LH}, T_{LC}, T_{AH}, T_{AC}) \quad (2)$$

$$Q_{DHX}^{rej} = \dot{m}_p \cdot c_p(\bar{T}_p) \cdot (T_{PH} - T_{PC}) \quad (3)$$

$$Q_{Loop}^{rej} = \dot{m}_L \cdot c_p(\bar{T}_L) \cdot (T_{LH} - T_{LC}) \quad (4)$$

$$Q_{AHX}^{rej} = \dot{m}_a \cdot c_p(\bar{T}_a) \cdot (T_{AH} - T_{AC}) \quad (5)$$

(1)~(5) P, L A ,

H C , \dot{m} Cp

[kg/s] (heat capacity : kJ/kg-K) , Cp

PDRC (design point)

$$(Q_{DHX}^{rej} = Q_{AHX}^{rej} = Q_{Loop}^{rej}) \equiv Q_{PDRC} \quad (6)$$

PDRC

(pressure drop) , KALIMER-600 PDRC

(flow resistance)

6 PDRC

6

(C)

가

(7)~(9)

가

$$C^P \cdot \dot{m}_P^2 = \Delta H(T_{PH}, T_{PC}, Z_C^+, Z_C^-, Z_D^+, Z_D^-, \beta_{TP}) \quad (7)$$

$$C^L \cdot \dot{m}_L^2 = \Delta H(T_{LH}, T_{LC}, Z_D^+, Z_D^-, Z_A^+, Z_A^-, \beta_{TL}) \quad (8)$$

$$C^A \cdot \dot{m}_a^2 = \Delta H(T_{AH}, T_{AC}, Z_A^+, Z_A^-, Z_{chm}^+, Z_{chm}^-, \beta_{TA}) \quad (9)$$

, C

[Pa·sec²/kg²]

P, L, A

, ΔH

(Z)

C, D, A chm

, DHX, AHX,

/

+ -

, β_T

(iteration)

, KALIMER-600 PDRC

UA

(1)~(5)

(7)~(9)

8 가

PDRC

(T_{PH})

(T_{AC})

4 , DHX AHX

{UA} 2 ,

(\dot{m})

3

9 가

, 1

UA

(10)

DHX AHX

{UA}

, R_{UA}

$$R_{UA} = \frac{\{UA\}_{DHX}}{\{UA\}_{AHX}} \quad (10)$$

9

PDRC (design point)

UA

(analytic solution)

, PDRC

3.2 PDRC

3.2.1 PDRC

KALIMER-600 PDRC

6 (A), (B) (C) (natural circulation head)

$$\Delta H_G^P = -\int \rho g ds = -\sum_i \rho_i g \Delta Z_i \tag{11}$$

$$= -g \cdot [\rho_{PC} \cdot (Z_D^- - Z_C^-) - \rho_{PH} \cdot (Z_D^+ - Z_C^+) + \bar{\rho}_P \cdot \{(Z_C^+ - Z_C^-) - (Z_D^+ - Z_D^-)\}]$$

$$\Delta H_G^L = -\int \rho g ds = -\sum_i \rho_i g \Delta Z_i \tag{12}$$

$$= -g \cdot [\rho_{LC} \cdot (Z_A^- - Z_D^-) - \rho_{LH} \cdot (Z_A^+ - Z_D^+) + \bar{\rho}_L \cdot \{(Z_D^+ - Z_D^-) - (Z_A^+ - Z_A^-)\}]$$

$$\Delta H_G^A = \sum_i \rho_i g \Delta Z_i = g \cdot [\bar{\rho}_a \cdot (Z_A^+ - Z_A^-) + \rho_{AH} \cdot \Delta Z_{chm}] \tag{13}$$

ΔH_G , P, L A
 ρ g (kg/m³) 가 (m/sec²)
 H C
 $\bar{\rho}$, DHX

AHX

3.2.2 PDRC

KALIMER-600 PDRC

(7)~(9) PDRC (C)

$$\dot{m} = \sqrt{\frac{\Delta H_G}{C}} \text{ [kg/sec]} \tag{14}$$

ΔH_G , C [Pa-kg²/sec²]

6 “ (pool) - DHX shell - (pool) -
 ” (A) “DHX tube -
 - AHX - DHX tube ”
 (B), shell
 AHX
 (C), C

3.2.2.1 PHTS

6 (A) PHTS [6]

KALIMER-150 IHX shell

DHX shell

PHTS

(pool structure)

C_{plst}

가

KALIMER-600 PHTS

(15)

PHTS

PHTS

(ΔH_G^P)

(16)

$$C_{PHTS,tot}^{SS} = C_{DHX,sh}^{SS} + C_{core}^{SS} + C_{plst} \quad (15)$$

$$\dot{m}_p = \sqrt{\frac{\Delta H_G^P}{C_{PHTS,tot}^{SS}}} \quad (16)$$

3.2.2.2 PDRC

KALIMER-600 PDRC

DHX

AHX

/

(friction loss)

(form loss)

[6]

PDRC

(17)

AHX

DHX

(ΔH_G^L)

KALIMER-600 PDRC

(18)

$$C_{f,tot}^{Loop} = C_{DHX,tube}^{Loop} + C_{f,pipe}^{Loop} + C_{f,tube}^{AHX} \quad (17)$$

$$\dot{m}_L = \sqrt{\frac{\Delta H_G^L}{C_{f,tot}^{Loop}}} \quad (18)$$

3.2.2.3 AHX shell

KALIMER-600

(AHX)

PDRC

(helical)

, AHX

가

가

AHX

가

AHX

, AHX

shell

AHX shell

(19)

AHX shell

AHX shell

(ΔH_G^A)

AHX shell

(20)

$$C_{f,tot}^{air} = C_{sh,air}^{AHX} + C_{chm,air}^{AHX} \quad (19)$$

$$\dot{m}_a = \sqrt{\frac{\Delta H_G^A}{C_{f,tot}^{air}}} \quad (20)$$

4. KALIMER-600 PDRC

KALIMER-600 PDRC

(analytic solution)

. PDRC

(analytic solution)

9

Newton-Rapson

Method[7] (Newton-Rapson Method with Multiple Equations and Unknowns)

$N \times N$ matrix

(21)

$$\begin{pmatrix} f_1 \\ f_2 \\ f_3 \\ \vdots \\ f_N \end{pmatrix} = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \frac{\partial f_1}{\partial x_3} & \dots & \frac{\partial f_1}{\partial x_N} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \frac{\partial f_2}{\partial x_3} & \dots & \frac{\partial f_2}{\partial x_N} \\ \frac{\partial f_3}{\partial x_1} & \frac{\partial f_3}{\partial x_2} & \frac{\partial f_3}{\partial x_3} & \dots & \frac{\partial f_3}{\partial x_N} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_N}{\partial x_1} & \frac{\partial f_N}{\partial x_2} & \frac{\partial f_N}{\partial x_3} & \dots & \frac{\partial f_N}{\partial x_N} \end{pmatrix} \cdot \begin{pmatrix} \Delta x_1 \\ \Delta x_2 \\ \Delta x_3 \\ \vdots \\ \Delta x_N \end{pmatrix} \quad (21)$$

(analytic solution)

$\Delta x_1 \sim \Delta x_N$

PDRC

(analytic

solution)

KALIMER-

600 PDRC

, Newton-Rapson Method

KALIMER-600 PDRC

(analytic solution)

, POSPA (Passive-safety grade decay heat removal circuit Overall System Performance Analyzer), POSPA

7

KALIMER-600 PDRC , DHX AHX UA
 , 1 , ,
 가 ,
 POSPA Iteration
 8
 8(a) 8(b) PDRC
 ,
 가 20 Iteration
 ($\epsilon_{diff} < 10^{-6}$)
 KALIMER-600 PDRC

4.

(Passive Decay heat Removal Circuit ; PDRC)

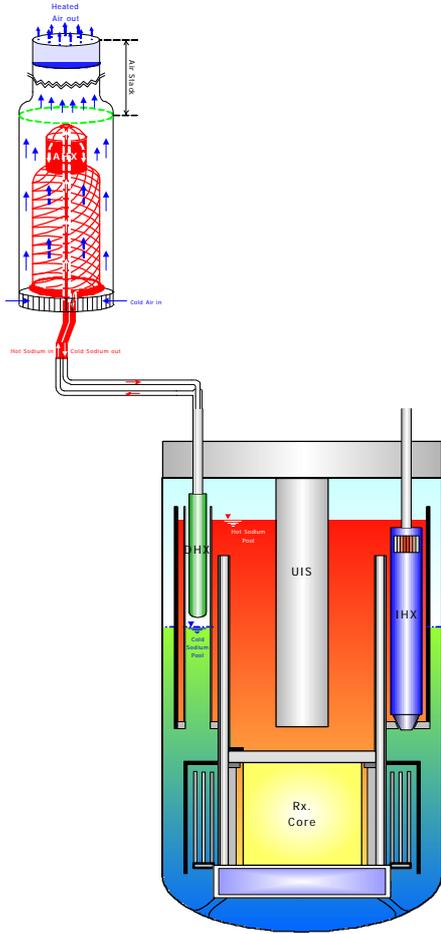
1589.3 MWth KALIMER-600
 (design point) PDRC . PDRC
 - DHX - AHX
 ,
 . PDRC
 , PDRC
 , DHX AHX
 , 9
 , POSPA
 . POSPA ,
 가 17 Iteration
 ,
 PDRC 가
 KALIMER-600 PDRC KALIMER-
 600 PDRC 가 .

[1] , " (2002)
 2002 (2002)

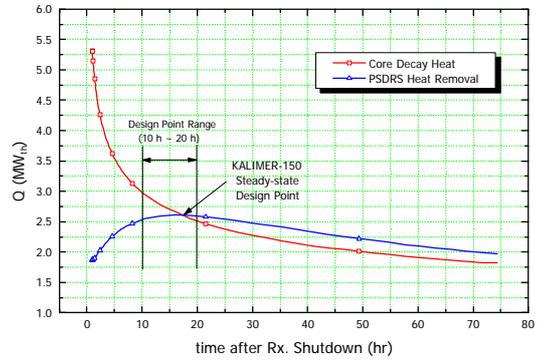
- [2] , " , " , 2003
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- [3] T. M. Darrington, "Non-Site-Specific safety Report", EFR Associates Draft, TOME1, FRAMATOME -Division NOVATOME (1993)
- [4] T. M. Darrington, "NSSSR-Nuclear Island and Division Concept (Chap.5.1)", EFR Associates Draft, TOME2, FRAMATOME -Division NOVATOME (1993)
- [5] , "KALIMER Conceptual Design Report", Korea Atomic Energy Research Institute, KAERI/TR-2204/2002 (2002)
- [6] , "KALIMER-600
",KAERI/TR-02653/2004
- [7] W.F. Stoecker, "Design of Thermal Systems", 3rd ed., McGRAW-Hill International Editions (1989)

1. KALIMER-600 PDRC

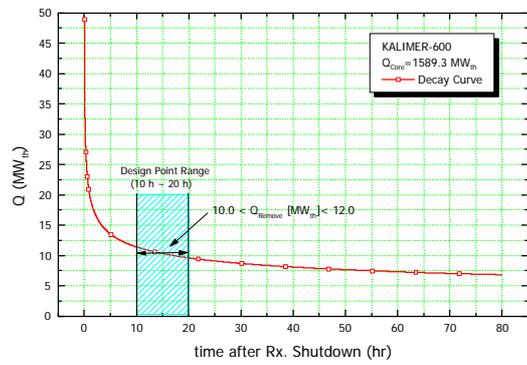
Description	Unit	Value	Remarks
Number of PDRC Loop	EA	2	Design Data
Number of DHX/AHX per Loop	EA/EA	2/2	Design Data
Total Required PDRC heat removal rate, $Q_{PDRC}^{req,tot}$	MWth	12.09	BC
Steady State Reached at time	hour	10	BC
POSPA Numerical Characteristics			
- Numbe of Iterations	-	21	
- Maximum % Difference	%	1.964E-10	
POSPA code Calculation Results			
{UA}_DHX	kW/°C	107.29	
{UA}_AHX	kW/°C	21.25	
{LMTD}_DHX	°C	56.35	
{LMTD}_AHX	°C	284.55	
PHTS hot pool Temperature	°C	547.86	BC
PHTS cold pool Temperature	°C	517.24	
PDRC hot leg Temperature	°C	326.12	
PDRC cold leg Temperature	°C	288.70	
AHX shell-side air inlet Temperature	°C	40.0	BC
AHX shell-side air outlet Temperature	°C	234.25	
PHTS pool sodium mass flowrate	kg/sec	37.13	
PDRC loop sodium mass flowrate	kg/sec	24.67	
AHX shell-side air mass flowrate	kg/sec	30.53	
PHTS pool total flow resistance	Pa-s ² /kg ²	1.981	
PDRC loop total flow resistance	Pa-s ² /kg ²	14.636	
AHX air-side total flow resistance	Pa-s ² /kg ²	0.3	
PHTS Pool Net Developing head	kPa	2.731	
PDRC loop net developing head	kPa	8.910	
AHX air-side developing head	kPa	0.280	



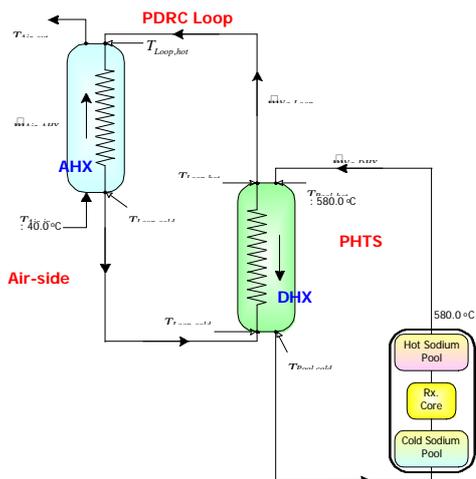
1. KALIMER-600 PDRC



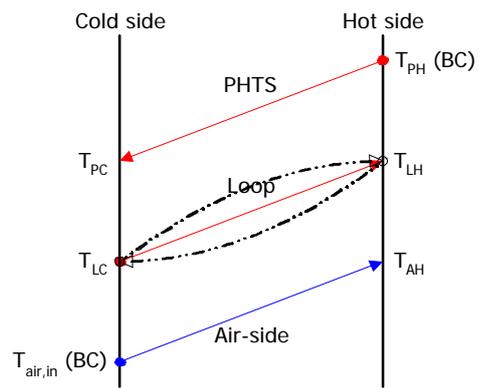
2. KALIMER-150



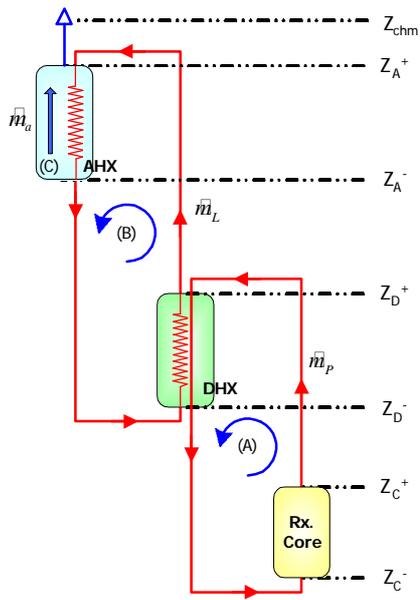
3. KALIMER-600 PDRC



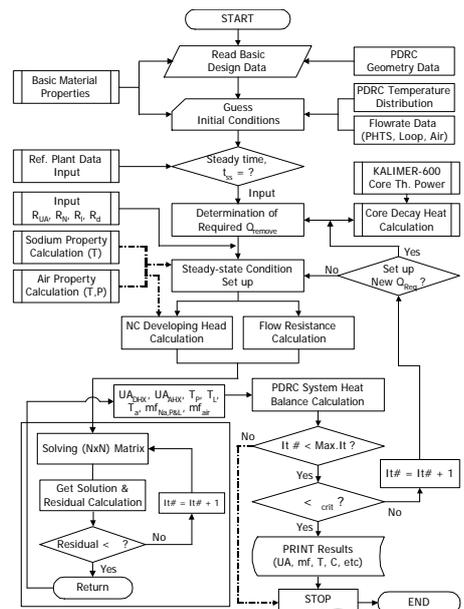
4. KALIMER-600 PDRC



5. KALIMER-600 PDRC

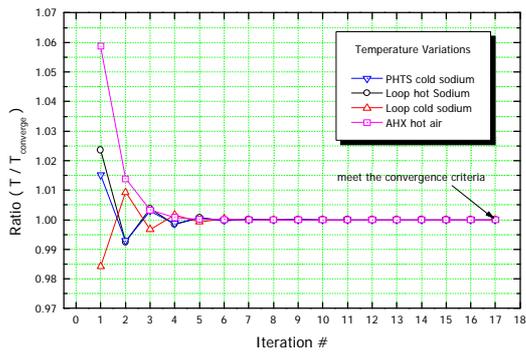


6. PDRC

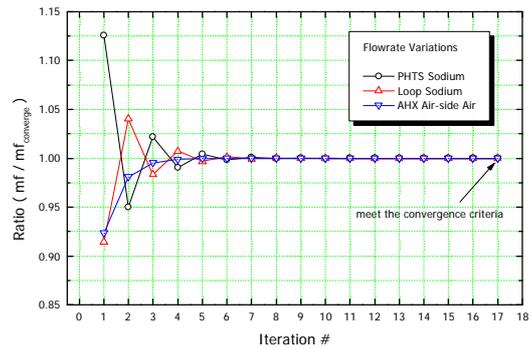


7. POSPA

(Flowchart)



(a) PDRC



(b) PDRC

8. POSPA