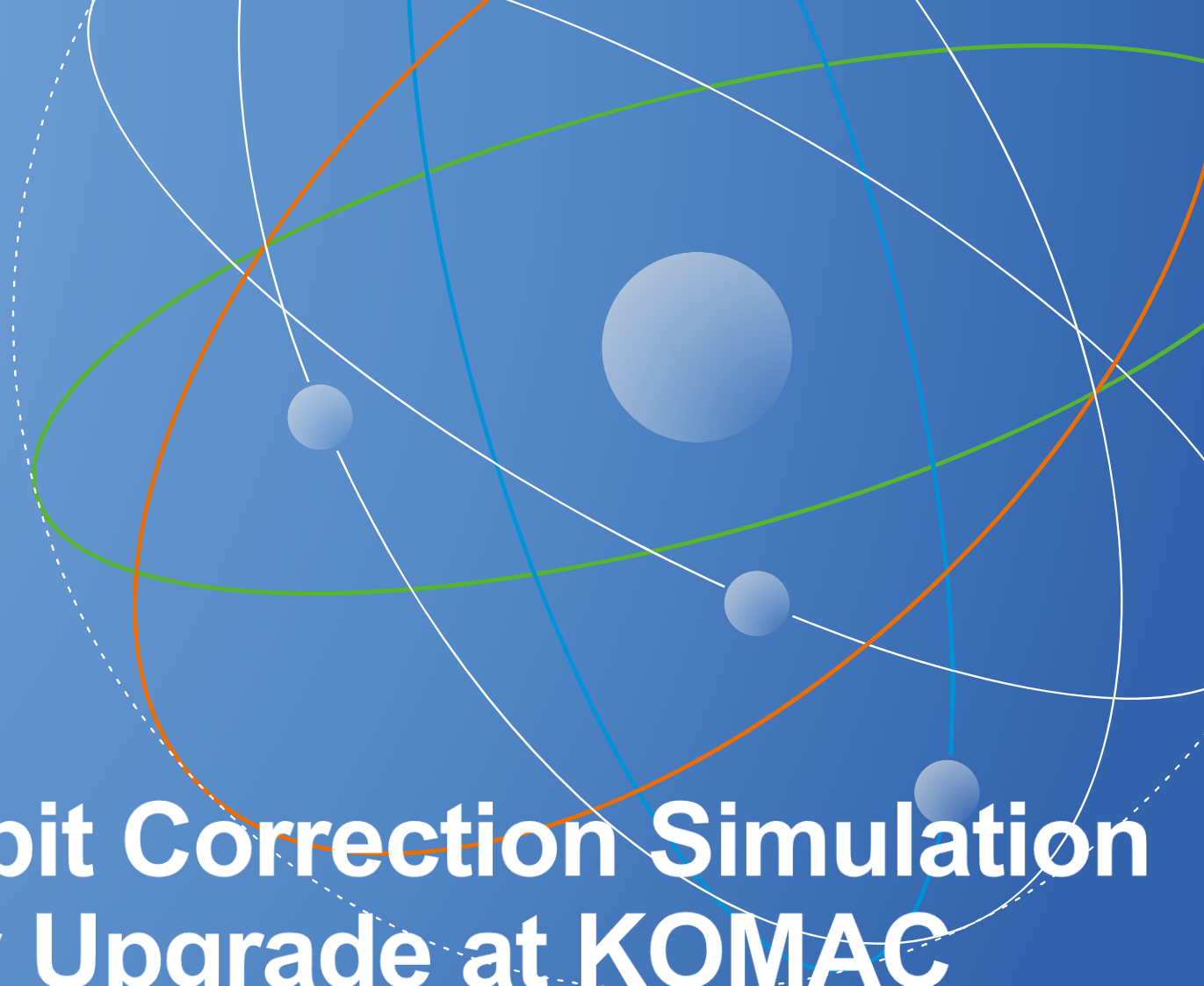


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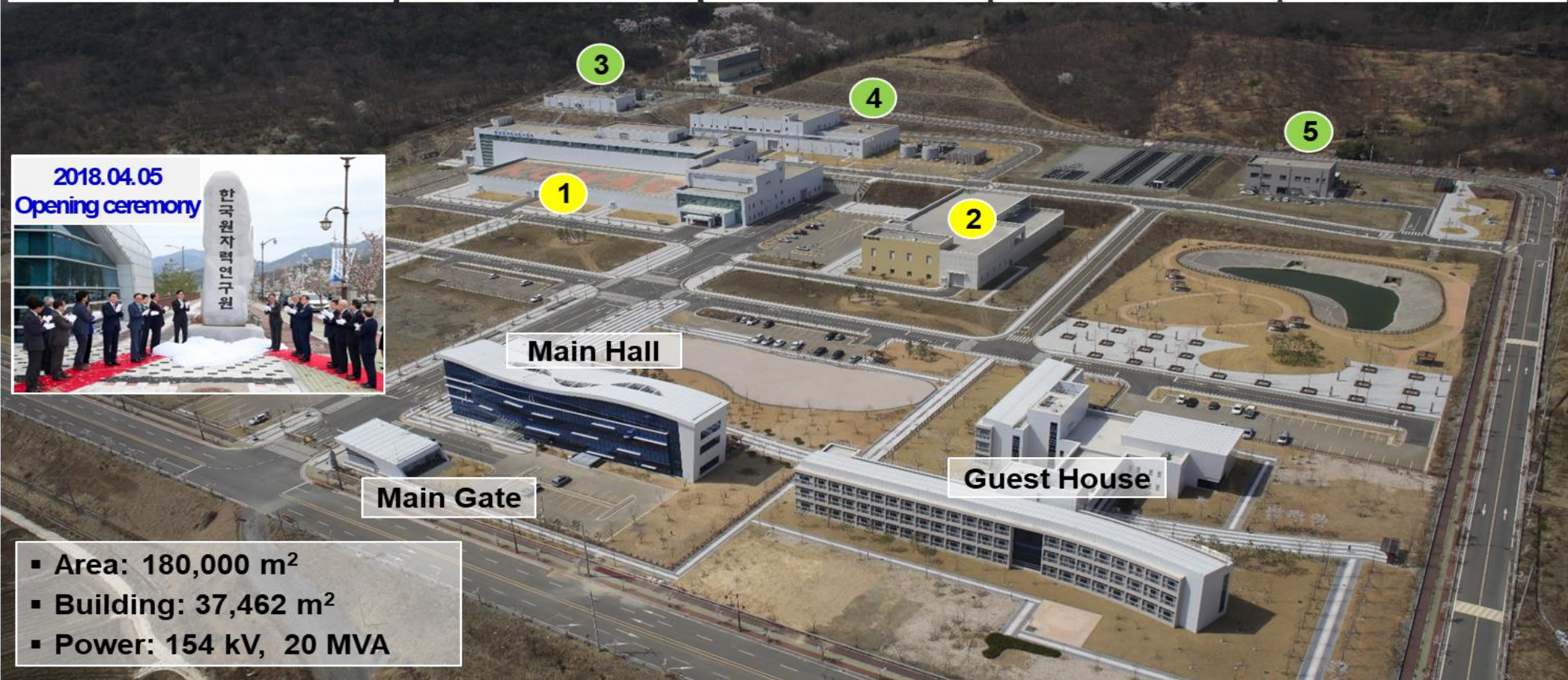
Error Study and Orbit Correction Simulation for 200 MeV Energy Upgrade at KOMAC

문석호, 이승현, 박성빈, 김동환, 김한성, 권혁중

10/24/2024

- **Introduction**
- **Beam dynamics and error study of 200 MeV LINAC**
- **Orbit correction simulation with error**
- **Summary**

Korea Multi-purpose Accelerator Complex



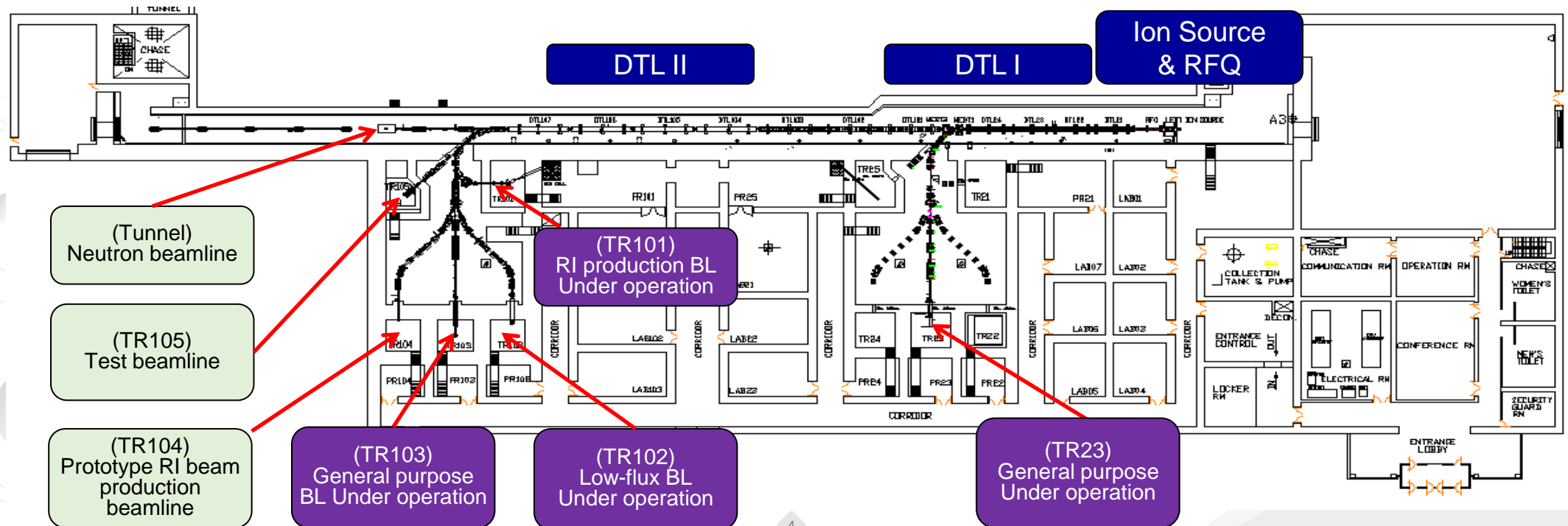
- Area: 180,000 m²
- Building: 37,462 m²
- Power: 154 kV, 20 MVA

100 MeV LINAC at KOMAC

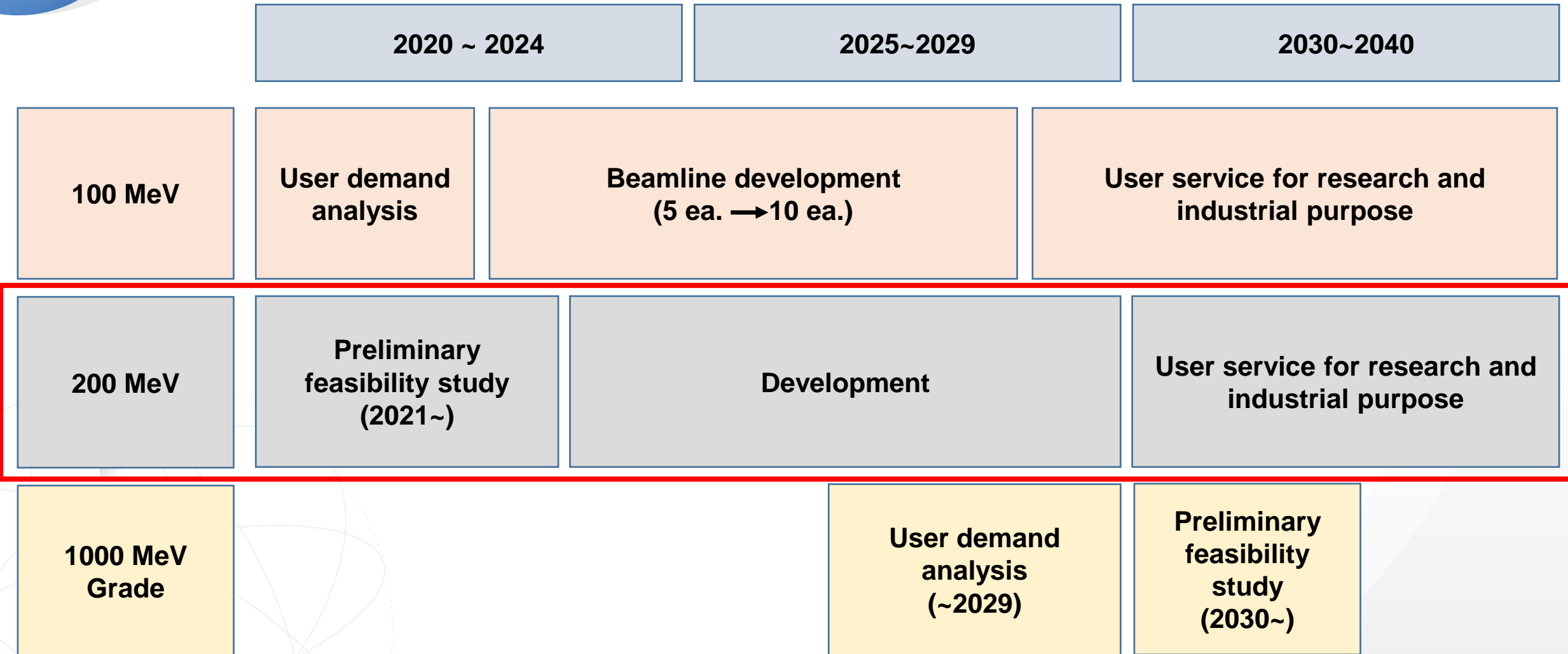
Features of KOMAC 100MeV linac

- 50-keV Injector (Ion source + LEBT)
- 3-MeV RFQ (4-vane type)
- 20 & 100-MeV DTL
- RF Frequency : 350 MHz
- Beam Extractions at 20 or 100 MeV
- 6 Beamlines for 20 MeV & 100 MeV

Output Energy (MeV)	20	100
Max. Peak Beam Current (mA)	1 ~ 20	1 ~ 20
Max. Beam Duty (%)	24	8
Avg. Beam Current (mA)	0.1 ~ 4.8	0.1 ~ 1.6
Pulse Length (ms)	0.1 ~ 2	0.1 ~ 1.33
Max. Repetition Rate (Hz)	120	60
Max. Avg. Beam Power (kW)	96	160

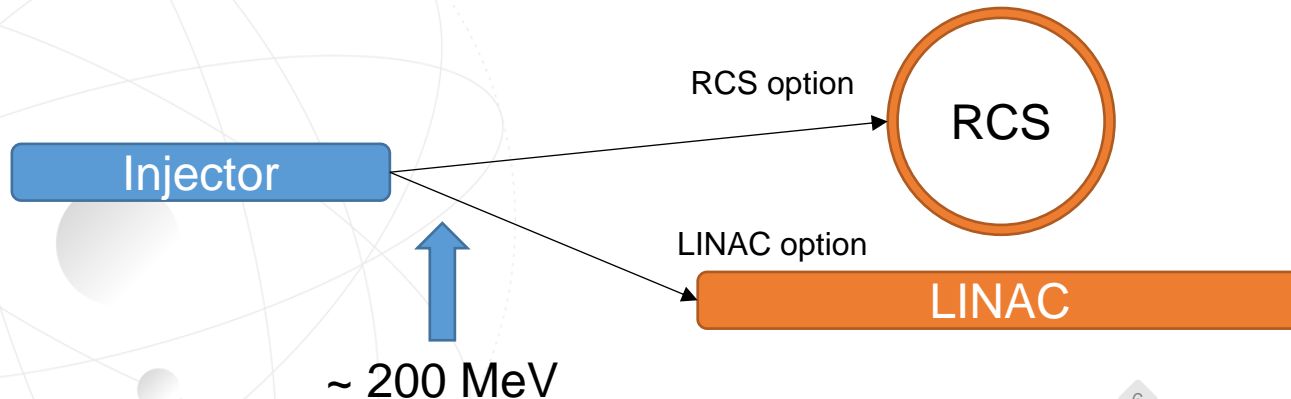


Roadmap of KOMAC



Why 200 MeV ?

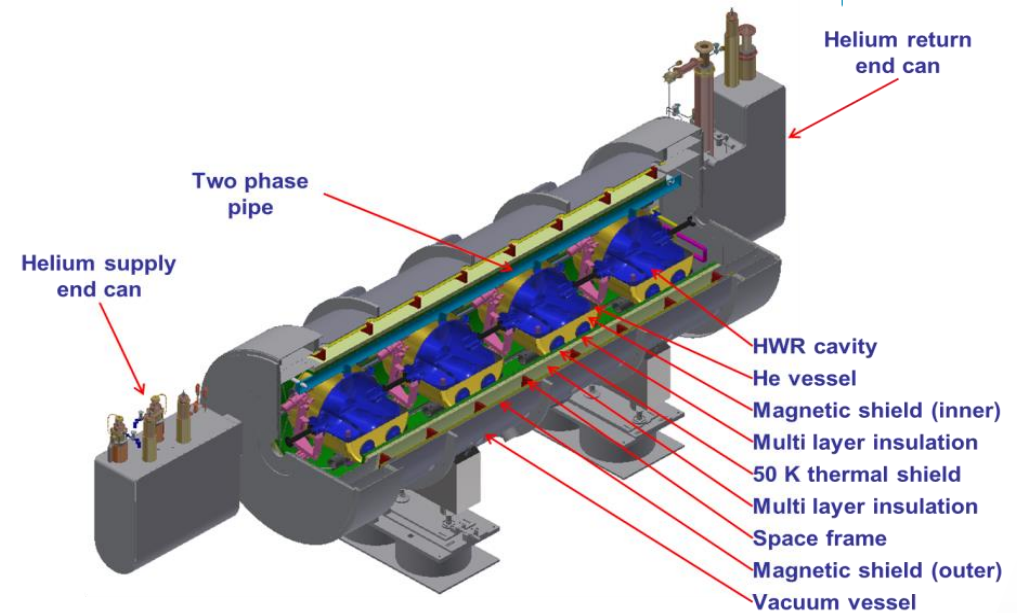
- Increasing demand
 - Terrestrial radiation test of semiconductor
 - Space radiation test of space parts
- Common to Short / long pulse neutron source
 - RCS injector: > 200 kW @ 1 GeV
 - Linac injector: accelerating structure transition
- 100 MeV -> 200 MeV
 - Single accelerator structure
 - Possible within existing site (without further site preparation)
- Required modifications for RCS option
 - H- source
 - MEBT (chopper)
 - Increasing beam current up to 40 mA



200 MeV LINAC Type Option 1: SC HWR

- Type: Superconducting HWR
- Use proven technology
- Cylindrical cryomodule
- 9 CMs, 36 HWRs from 100 to 200 MeV

Parameter	Unit	KOMAC HWR(0603)	FRIB (2013)
Frequency	MHz	350	322
Optimum beta	-	0.56	0.53
Stored energy	J	23.1	29.48
V_{acc} (@ β_{opt})	MV	3.61	3.7
V_0	MV	4.14	-
E_{acc} (@ β_{opt})	MV/m	7.53	7.5
E_0	MV/m	8.63	-
E_p	MV/m	29.08	26.5
B_p	mT	61.66	63.2
E_p/E_{acc}	-	3.86	3.53
B_p/E_{acc}	mT/(MV/m)	8.19	8.43
R/Q (@ β_{opt})	ohm	256.6	229.5
G	ohm	116.1	107.4
Q_0 (@ $R_s=20$ n Ω)	-	5.81E+9	-
Cavity loss (@ $R_s=20$ n Ω)	W	8.75	7.9
Aperture	mm	40	40
L_{eff} ($\beta_{opt}\lambda$)	m	0.480	0.493
Cavity inner diameter	m	0.45	0.46



- CM length: 3,600 mm (5,430 mm including end cans)
- CM diameter: 1,200 mm
- Heat load per CM

	2 K	50K
Static	11.0 W	144 W
Dynamic	8.1 W	-
U-tube and line*	10 W	24 W
Total	29.1 W	168 W

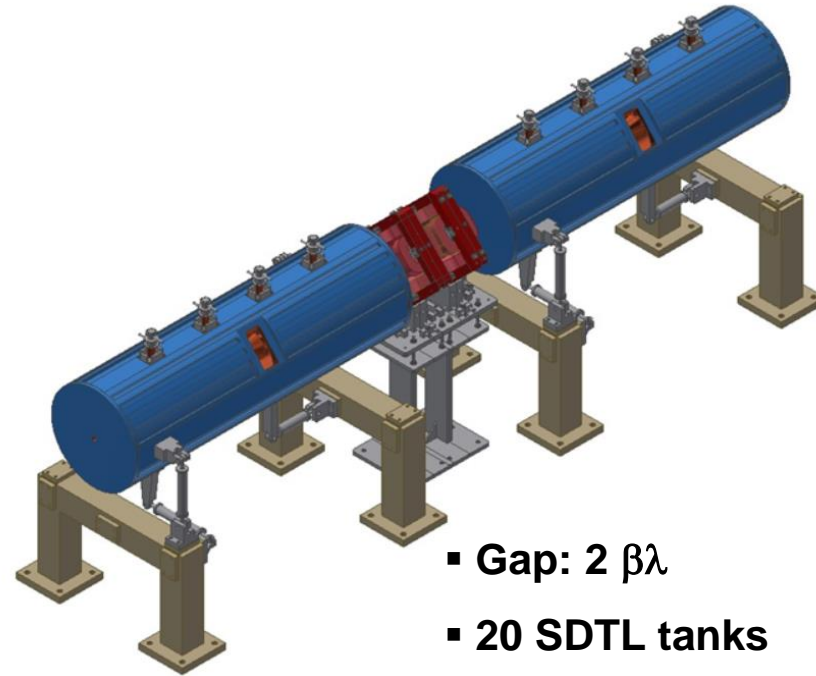
130 W** (4.5 K equivalent) / cryomodule

* Ref. SNS cryomodule parameter

** Including 25% margin

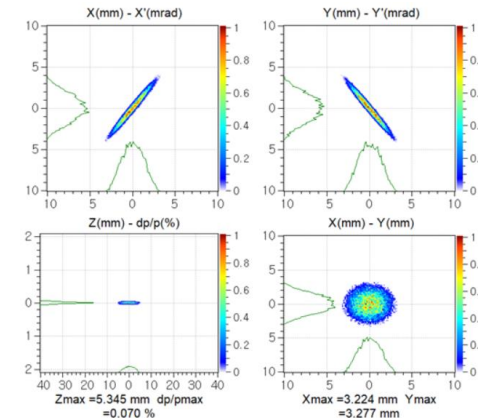
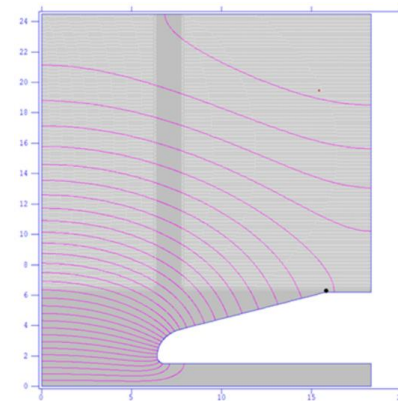
200 MeV LINAC Type Option 2: NC SDTL

- Type: Separate Drift Tube Linac
- Use proven technology
- Doublet focusing external to cavity
- Cell optimization for ZTT
- Kilpatrick < 1.5
- RF power per tank < 1.2 MW @ 40 mA



- **Gap: $2 \beta \lambda$**
- **20 SDTL tanks**
- **Total length: 60 m**

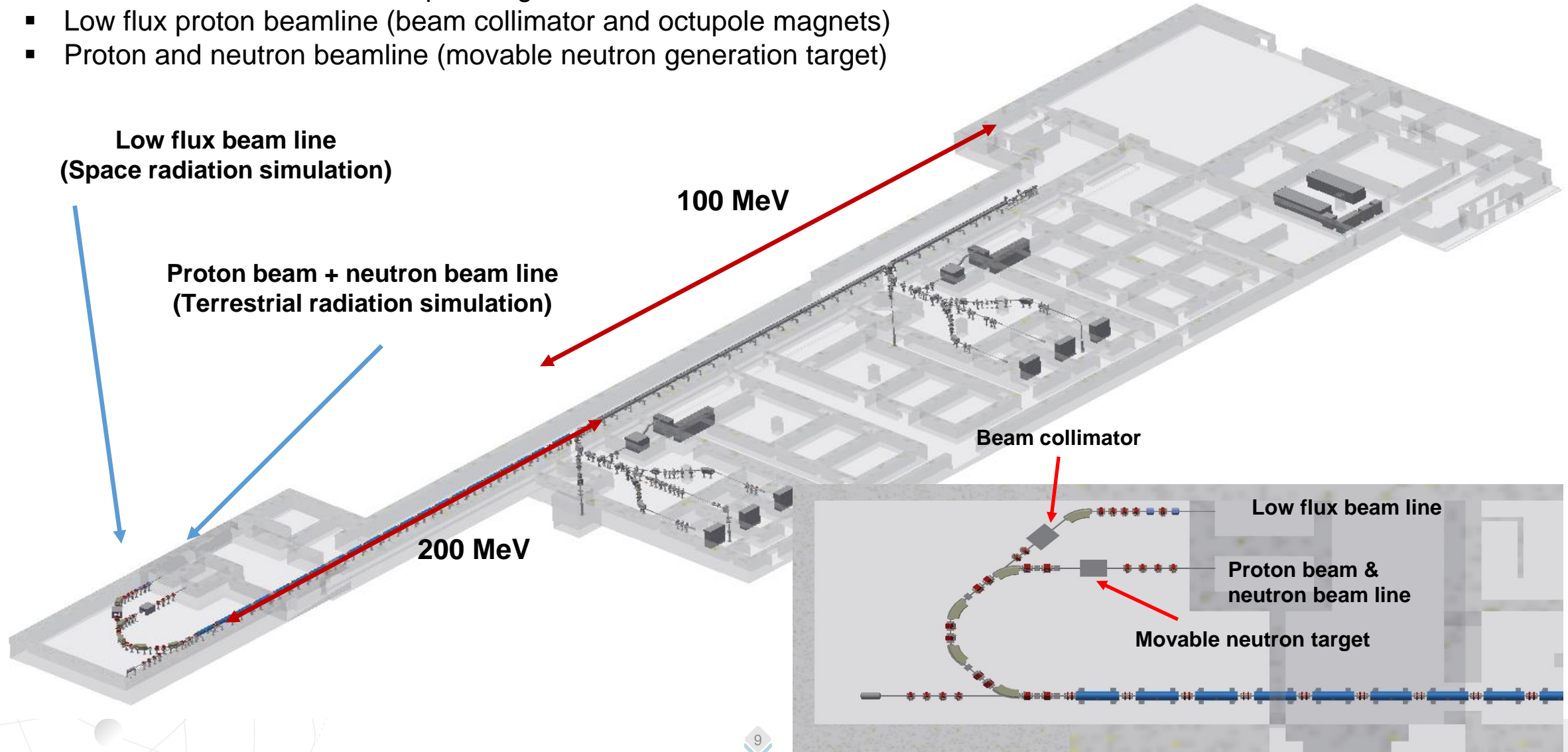
Parameter	Unit	KOMAC SDTL
Frequency	MHz	350
Number of tanks	-	20
Input energy	MeV	102.6
Output energy	MeV	200
Tank length	m	1.9 ~ 2.4
Number of DT	-	4
Number of cell	-	5
Tank inner diameter	mm	491.6



200 MeV Layout (NC SDTL-type)

Based on user demand, we are planning to install two beamlines

- Low flux proton beamline (beam collimator and octupole magnets)
- Proton and neutron beamline (movable neutron generation target)

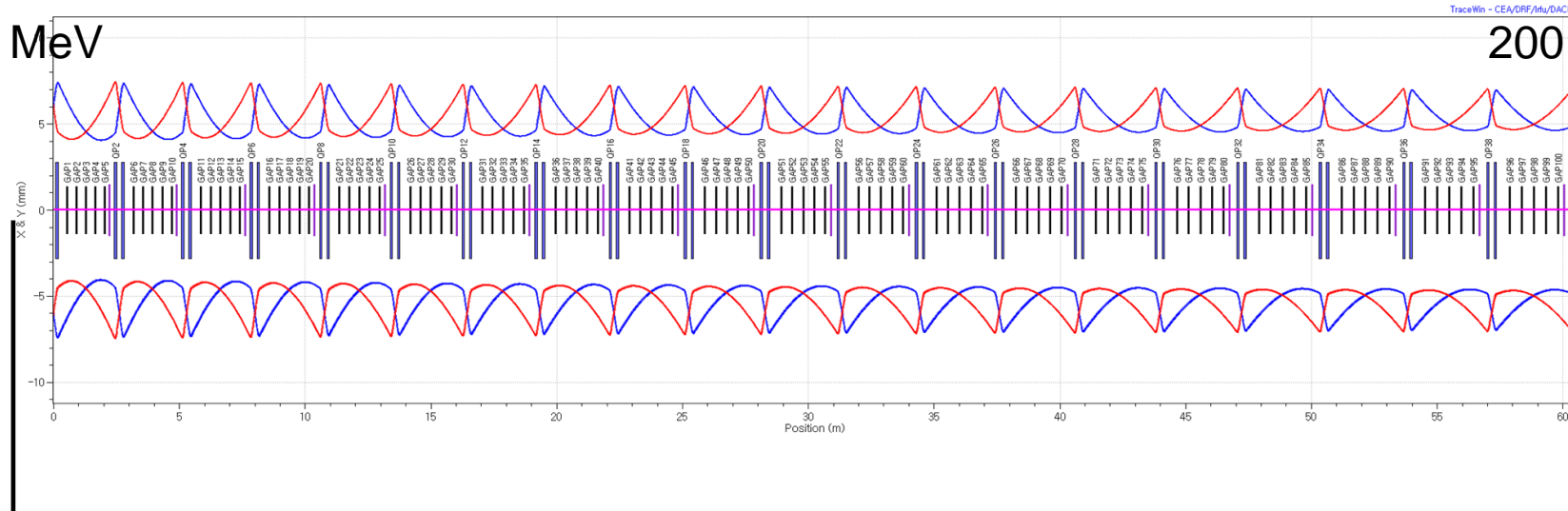


- Introduction
- **Beam dynamics and error study of 200 MeV LINAC**
- Orbit correction simulation with error
- **Summary**

200 MeV Energy Upgrade Beam Dynamics

100 MeV

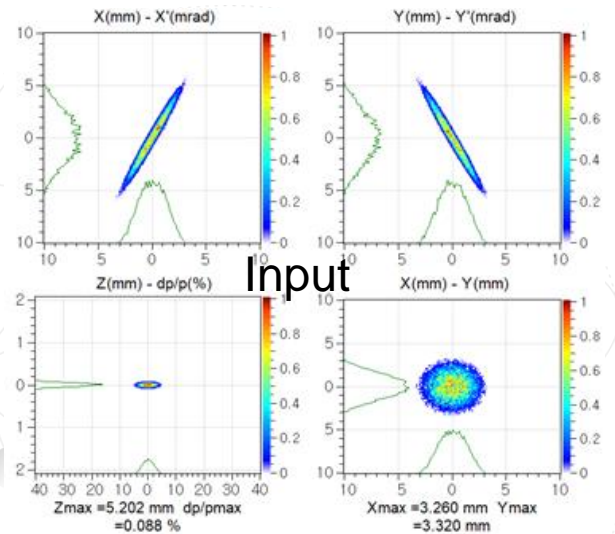
200 MeV



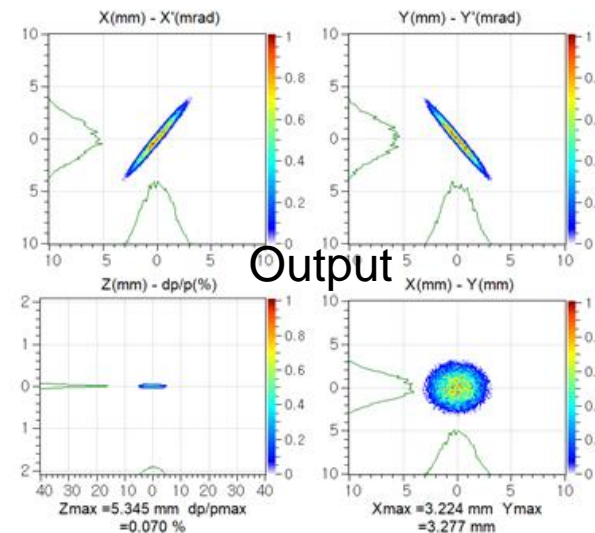
Initial current : 20mA

Initial energy: 100 MeV

Output energy: 200 MeV

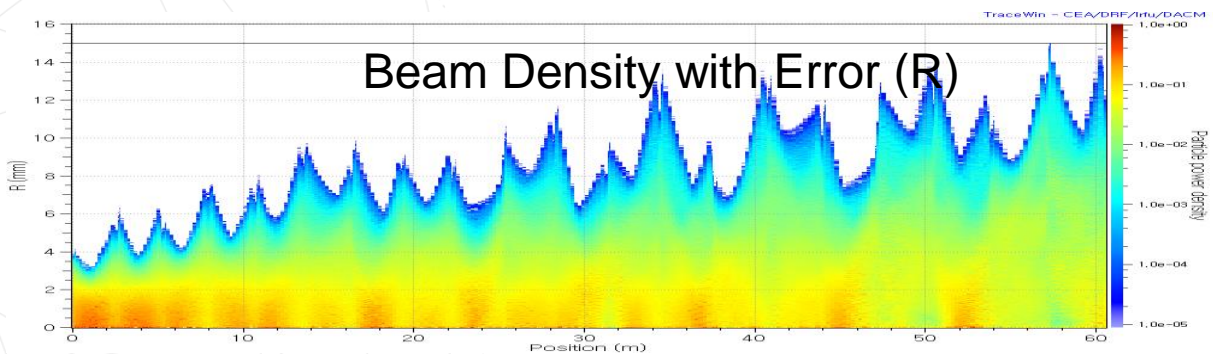
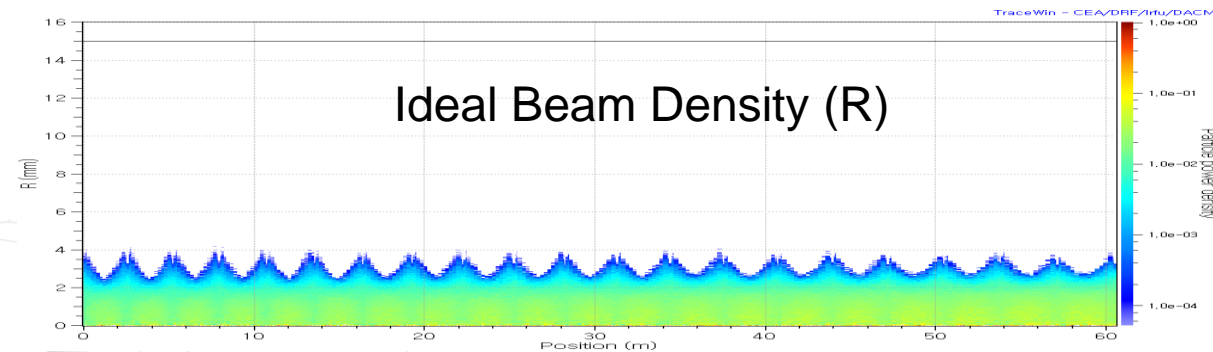
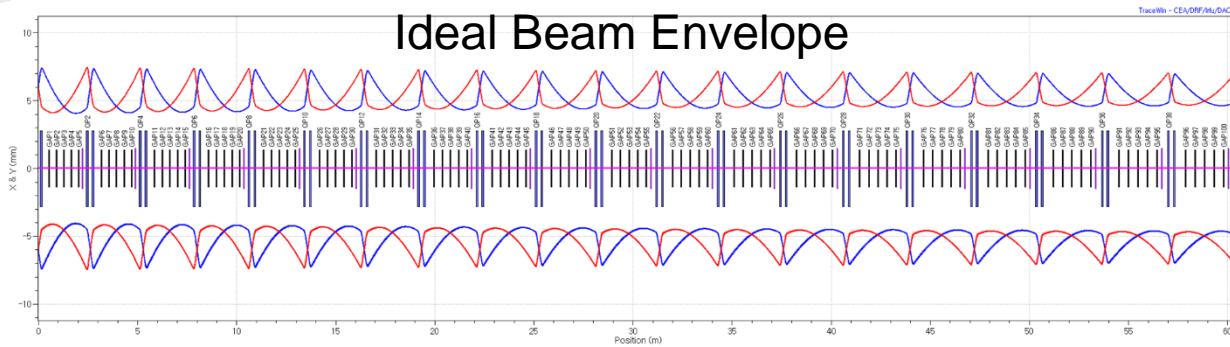


	Emit (Norm, rms)	α	β (m)
X	0.224	-5.416	3.072
y	0.226	5.447	3.122
Z	0.295	-0.023	5.961

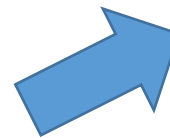
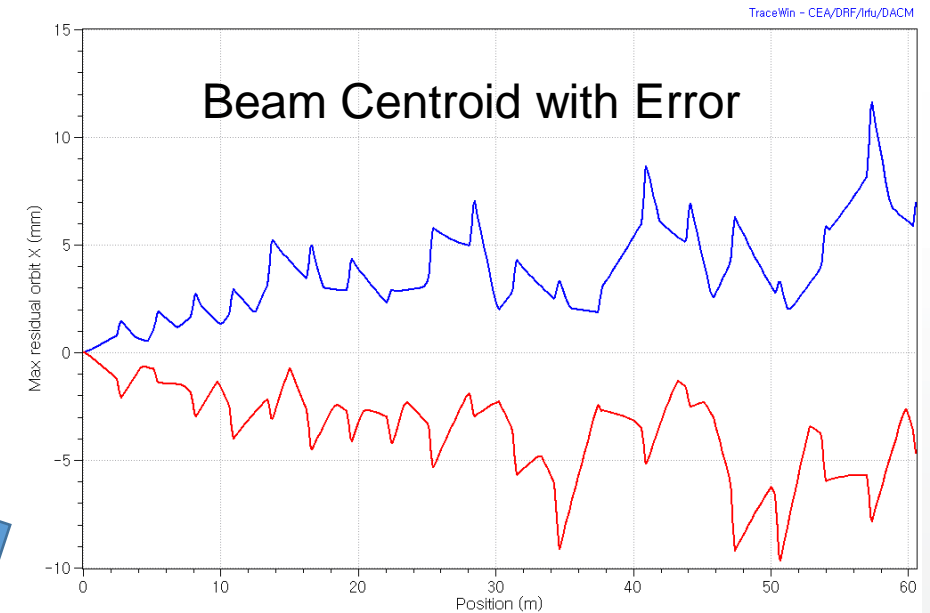


	Emit (Norm, rms)	α	β (m)
X	0.225	-5.474	4.395
y	0.227	5.421	4.387
Z	0.302	0.035	10.48

200 MeV Energy Upgrade Error Study



Why Error Study?



External error change the beam dynamics

We need to set **Criteria**

Error Study Setup

Beamline Error (Quad, Cavity)

Error Type	Value
Quad magnet displacement (dx, dy)	$\pm 300 \mu m$
Quad magnet rotation (ϕ_x, ϕ_y, ϕ_z)	$\pm 0.5^\circ$
Quad magnet gradient	$\pm 3\%$
Cavity displacement (dx, dy)	$\pm 300 \mu m$
Cavity rotation (ϕ_x, ϕ_y)	$\pm 0.5^\circ$
Cavity Acc. Voltage	$\pm 3\%$
Cavity Phase (ϕ_{sync})	$\pm 3^\circ$

of Error lattice: 200 (10 lattice * 20 step)

Error statistical set up: 10 lattice per 1 step

Input Beam Error

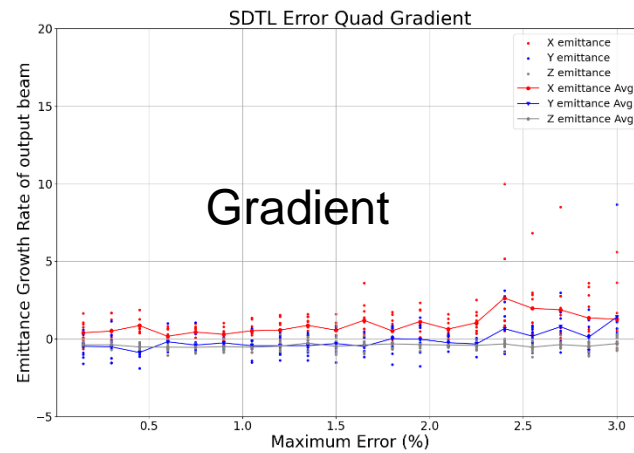
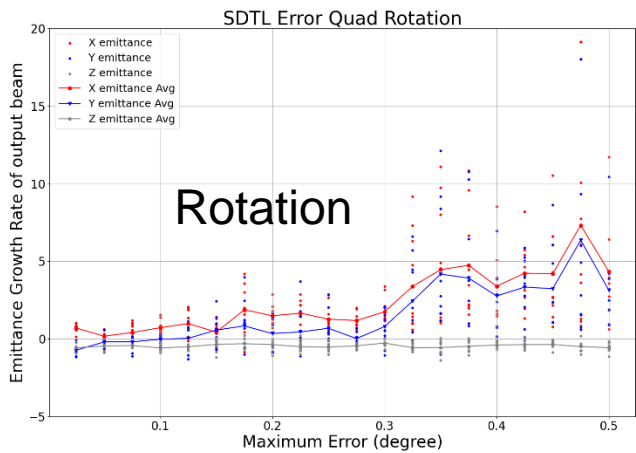
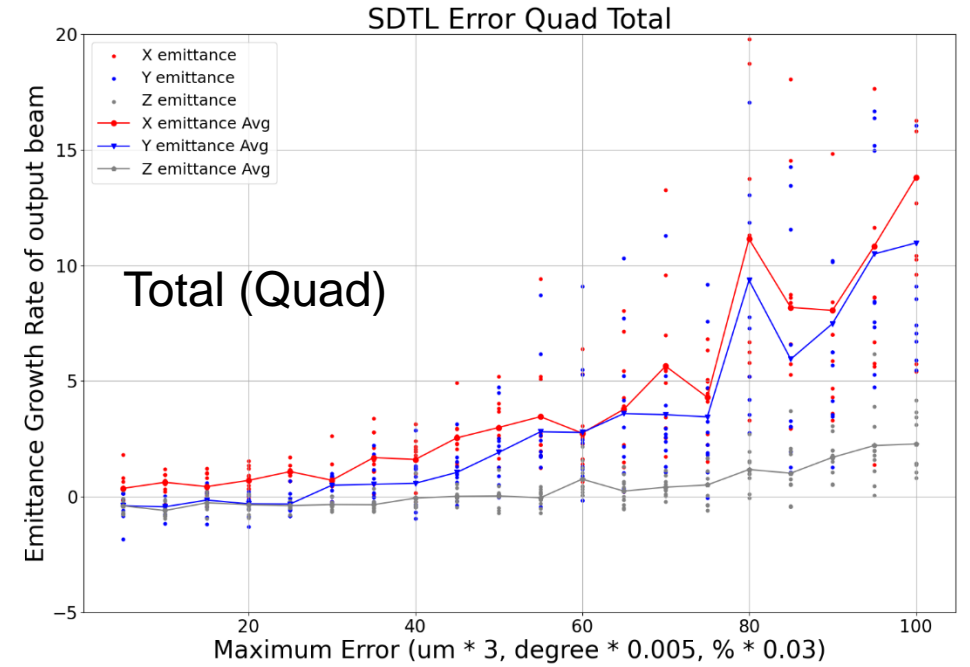
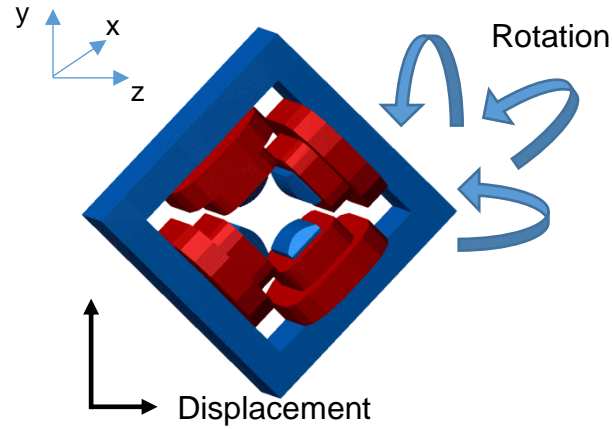
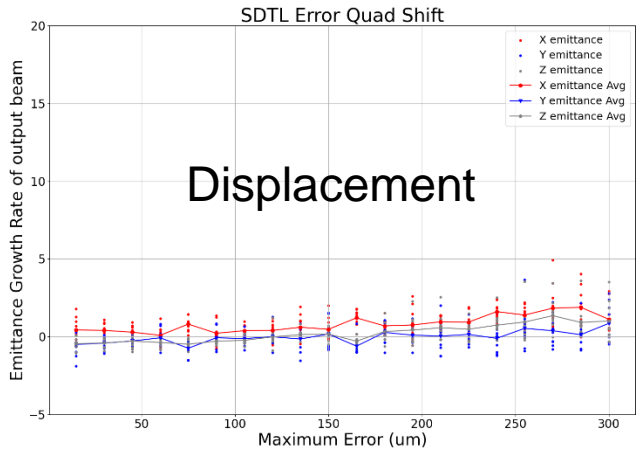
Error Type	Value
Input beam center (x)	$\pm 2.5 \text{ mm}$
Input beam angle (y)	$\pm 5 \text{ mrad}$
Input beam center (x)	$\pm 2.5 \text{ mm}$
Input beam angle (y)	$\pm 5 \text{ mrad}$
Input beam matching (x)	150 %
Input beam matching (y)	150 %
Input beam matching (x)	150 %

Error distribution type: Uniform distribution

Input Beam Current : 20 mA

Error Study with Quad Magnet Error

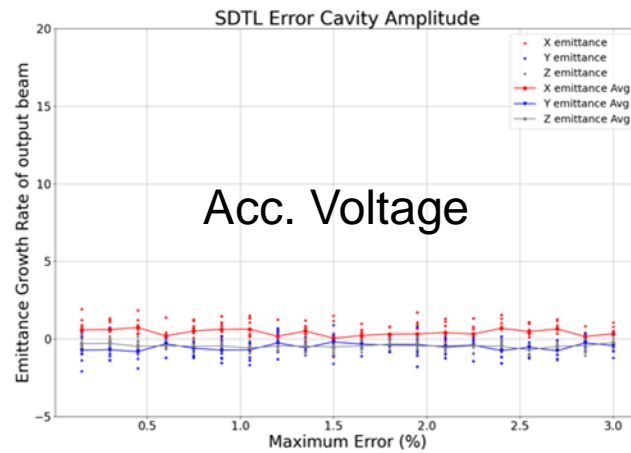
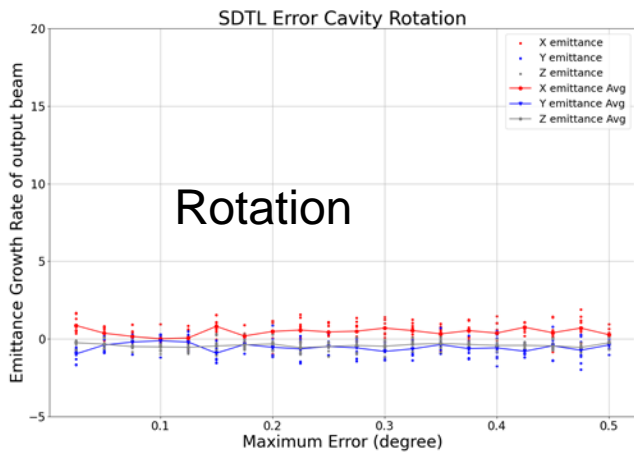
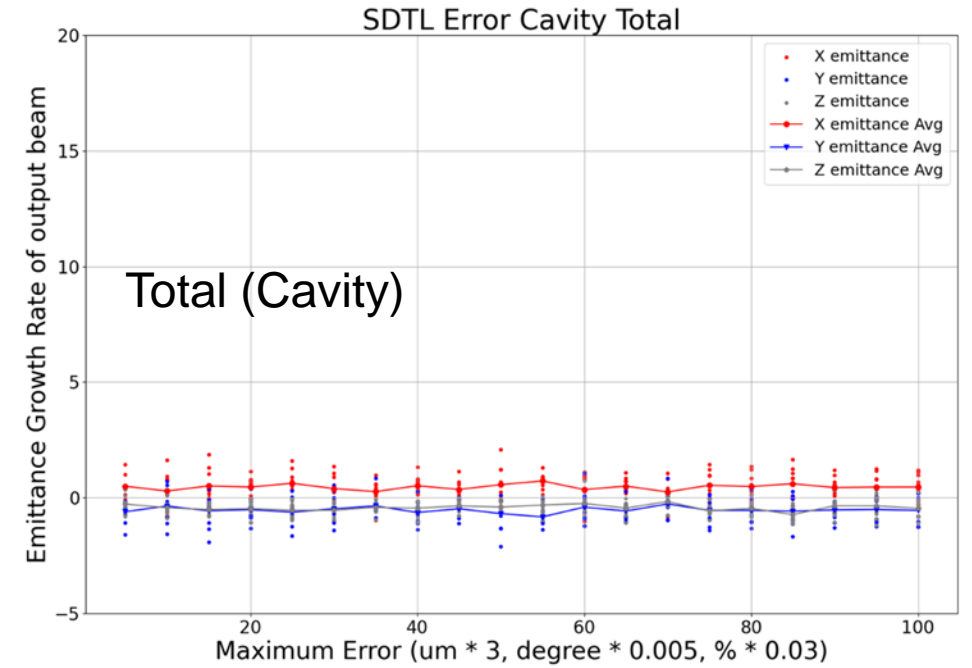
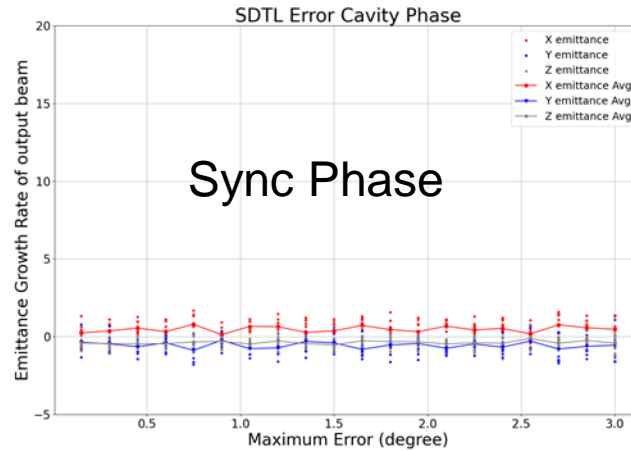
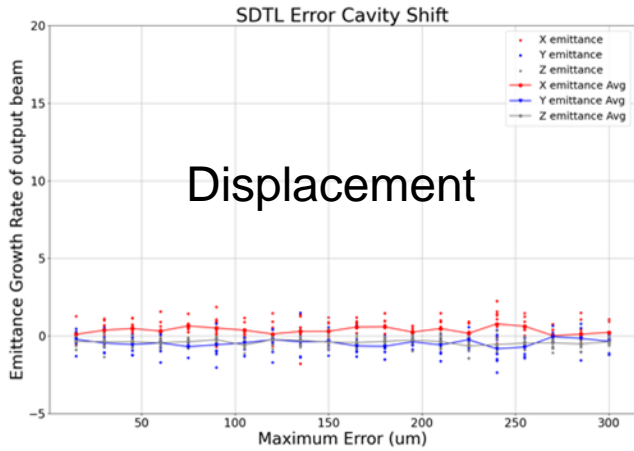
Beamline Error (Quad)



Max emittance growth : ~ 10 %

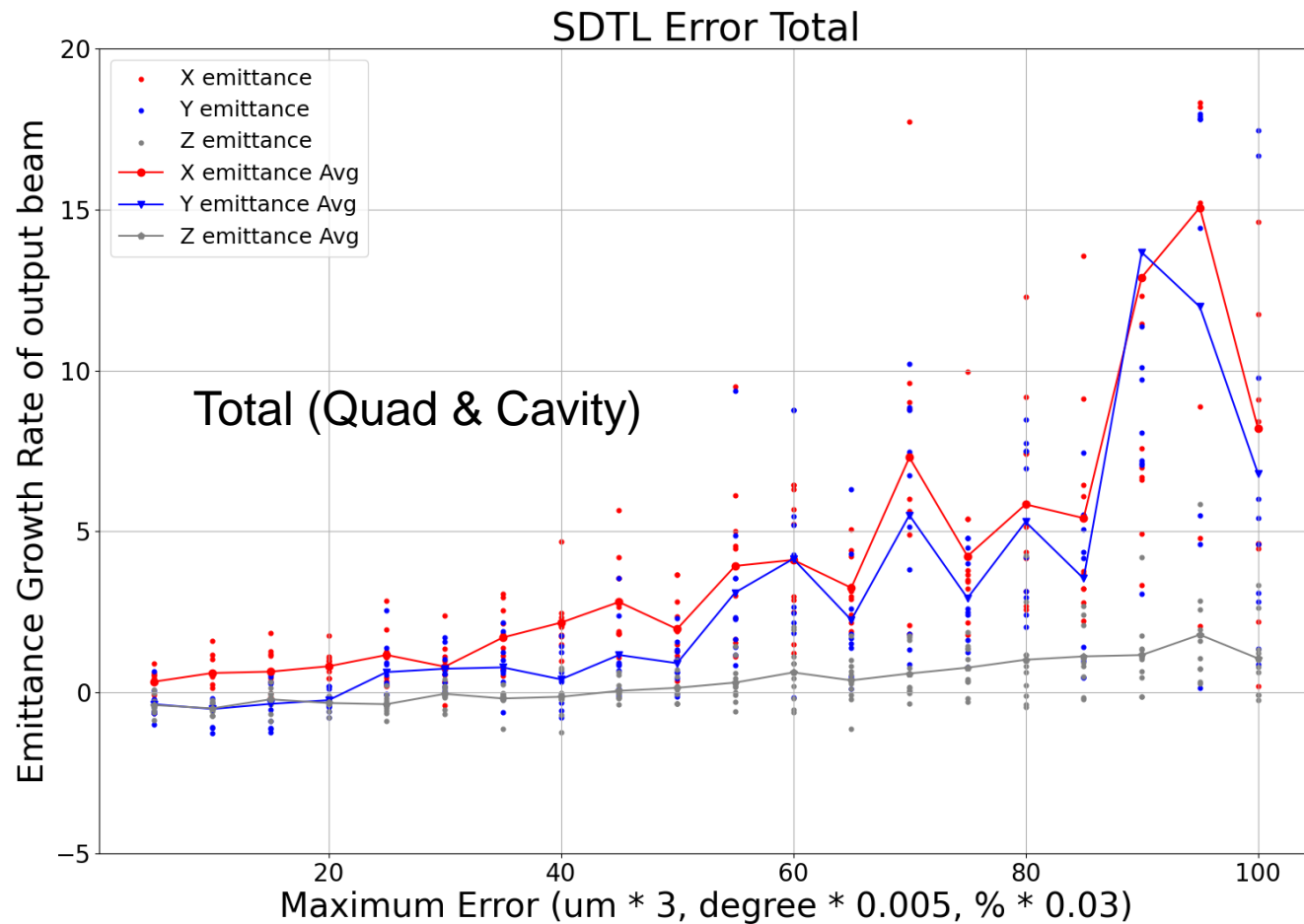
Error Study with Cavity Error

Beamline Error (Cavity)



Almost non-effective

Error Study with All types of Error



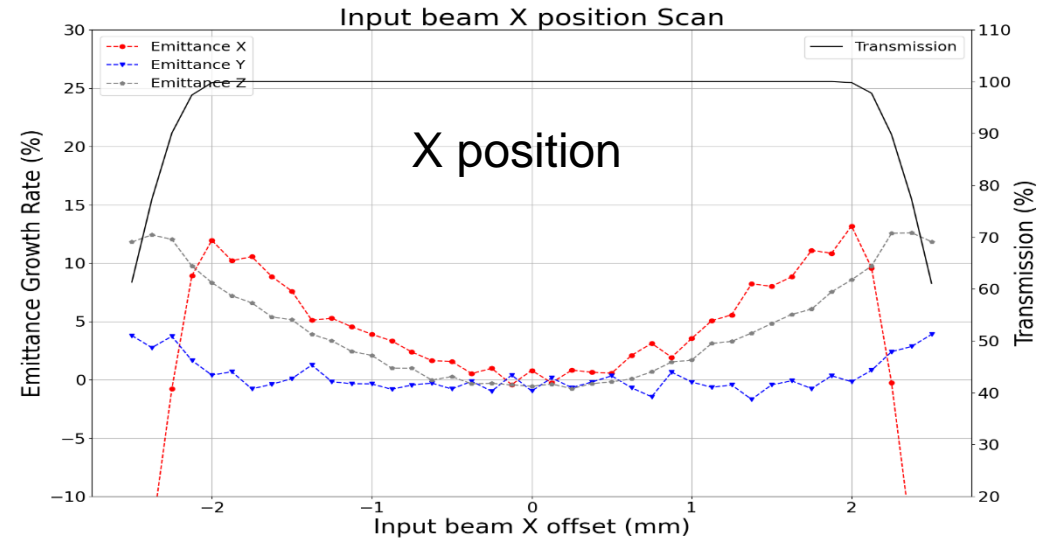
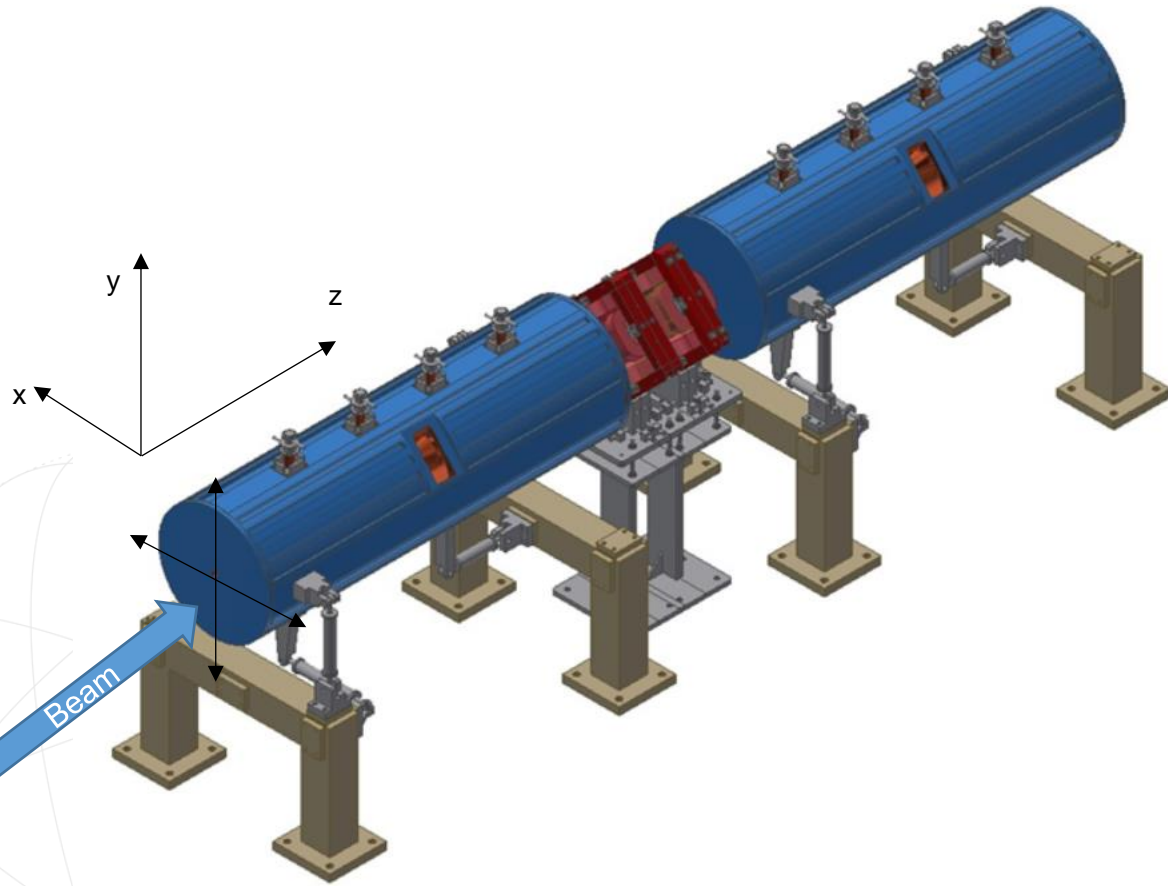
Error from quad magnet is **dominant**

but not **Significant**

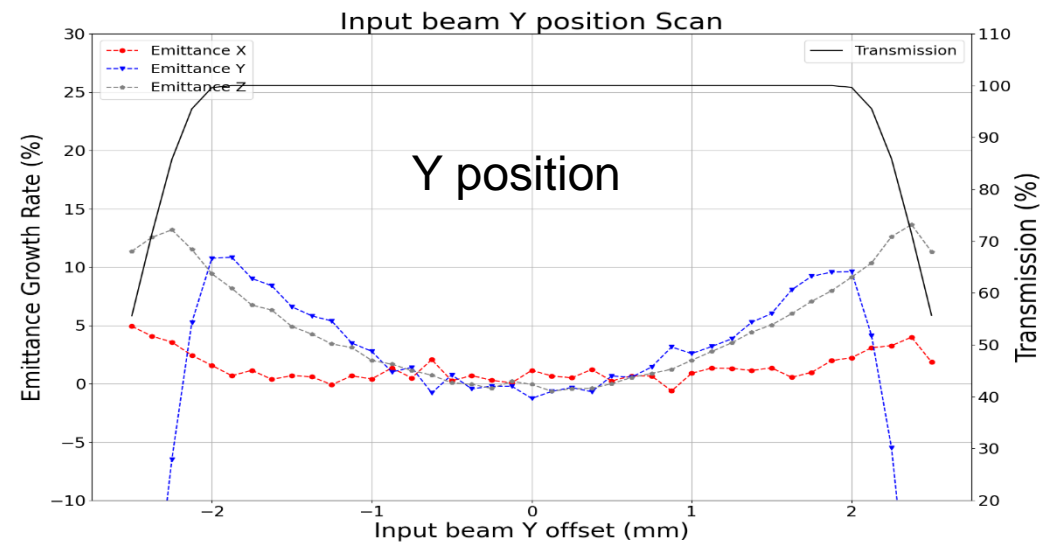
In terms of emittance growth

Input Beam Centroid Shift

Input Beam Error (Centroid Shift)

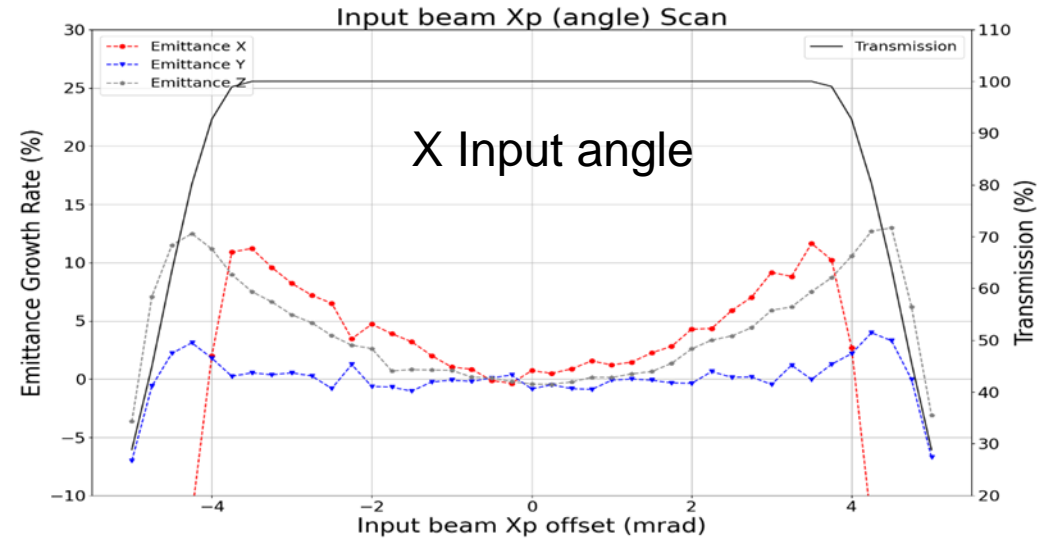
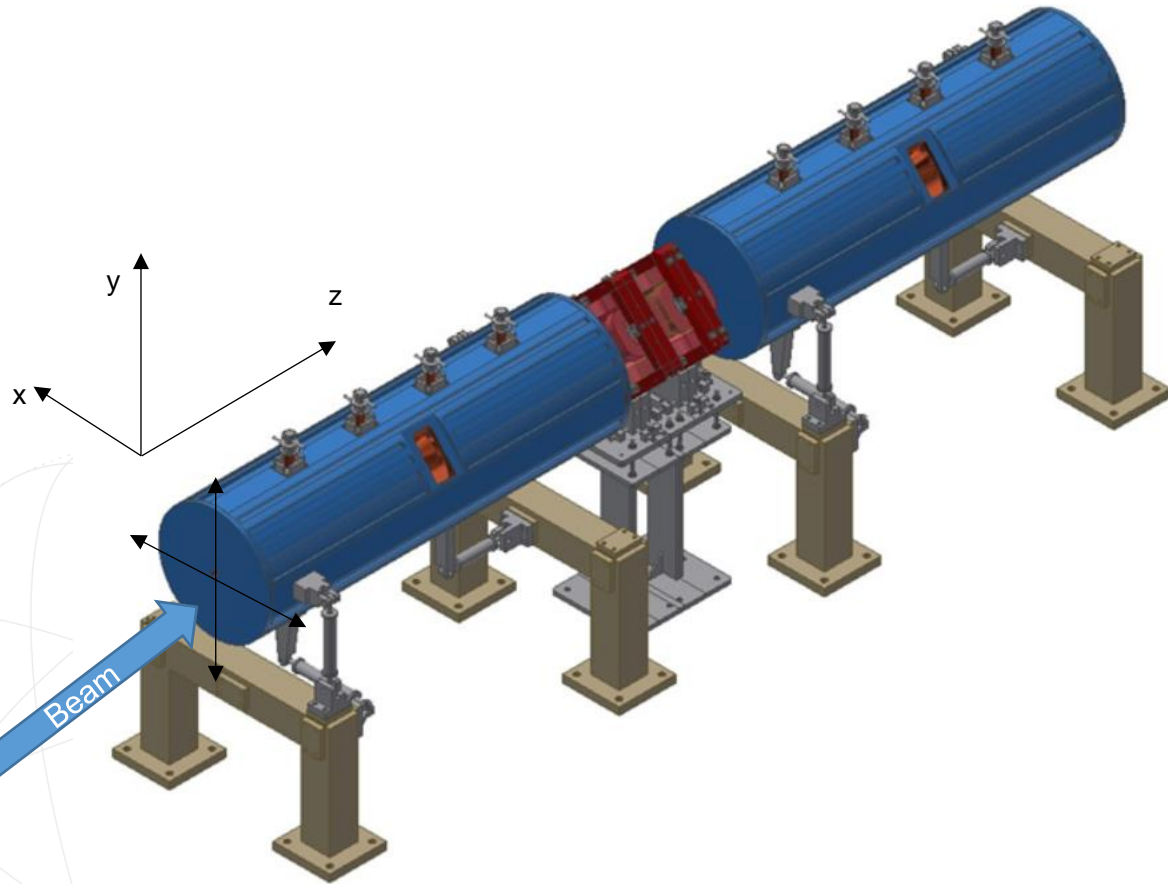


Very significant

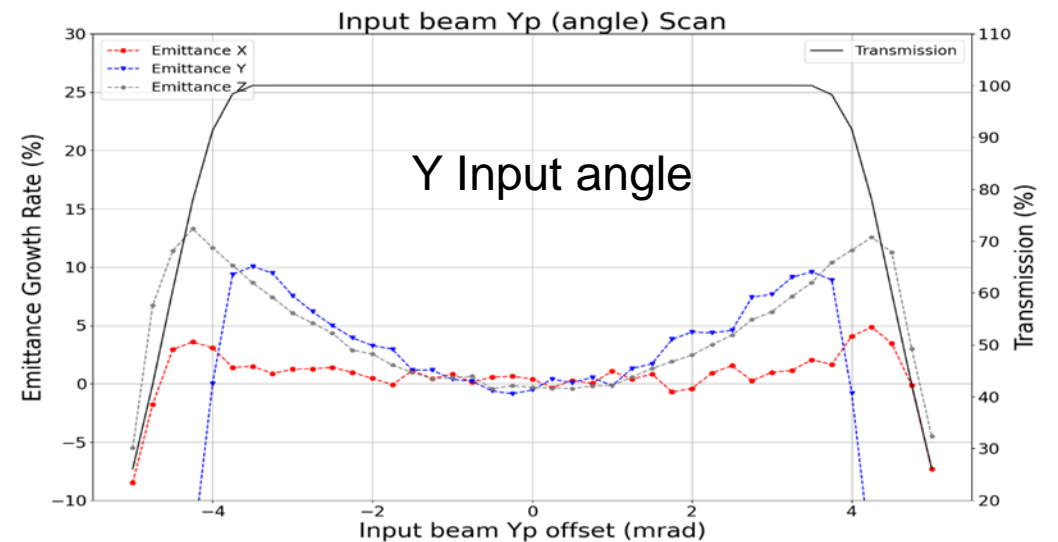


Input Beam Angle Shift

Input Beam Error(Input beam angle)



Very significant



- Introduction
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- **Orbit correction simulation with error**
- Summary

Orbit Correction Simulation Setup

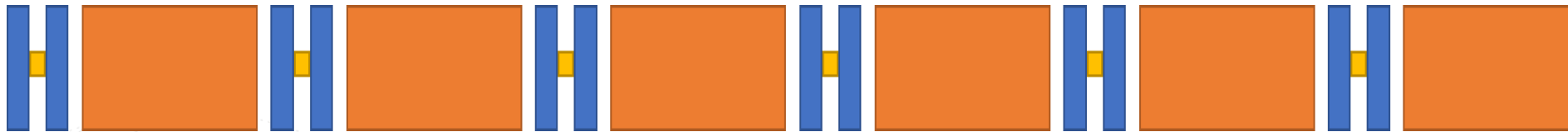
Steer type 1 (Both x, y)



Steer type 2 (x, y separate)



Installation type 1



Total Case : 6

Steerer type * Installation type

Installation type 2



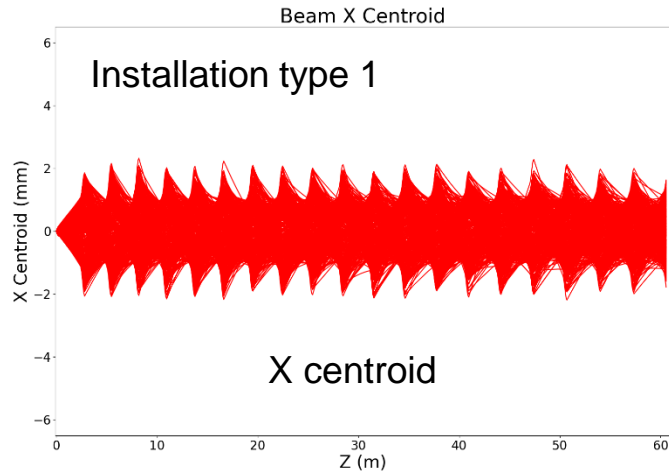
Input error : Beamline error

Installation type 3

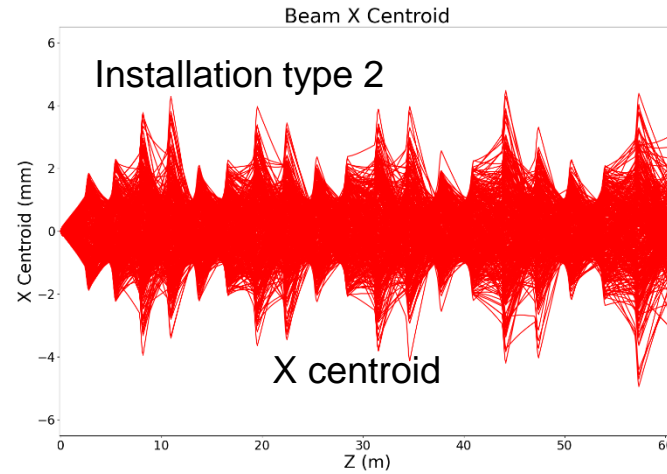
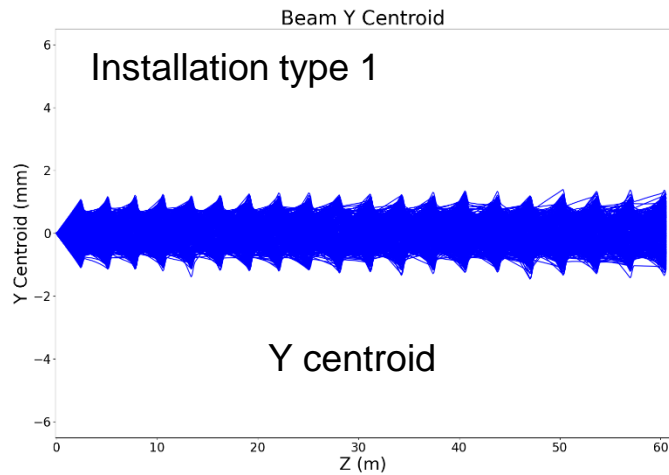


Orbit Correction Simulation Centroid Result 1

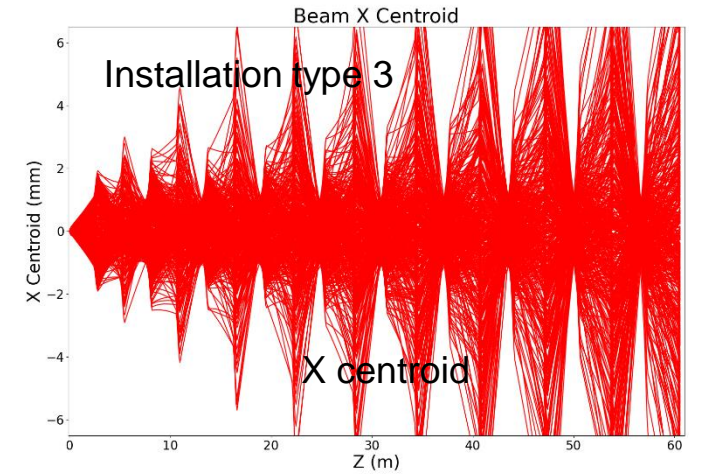
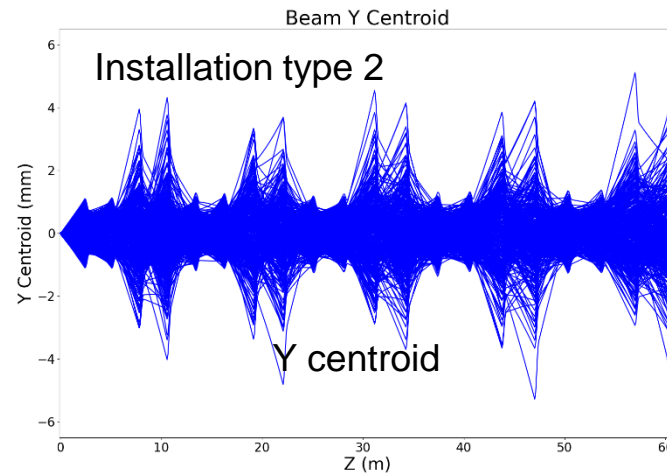
Steer type 1



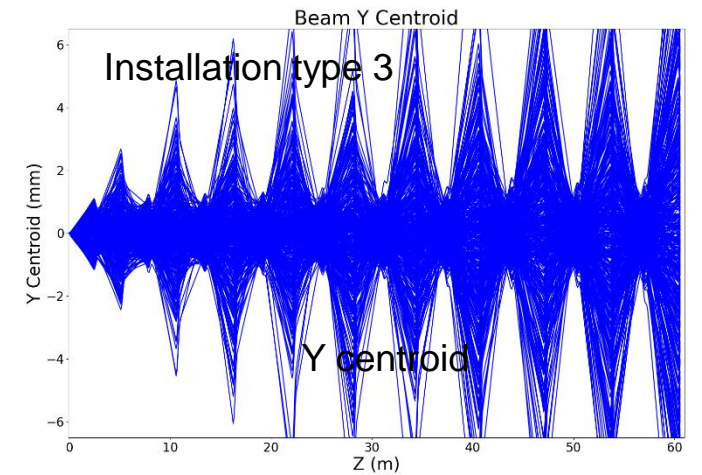
Possible



Possible

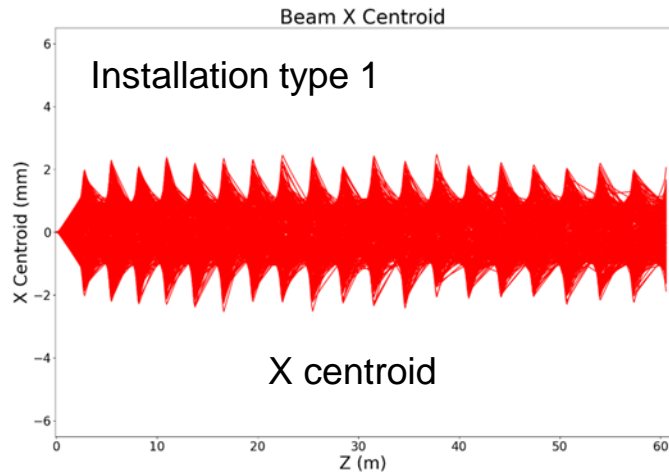


Impossible

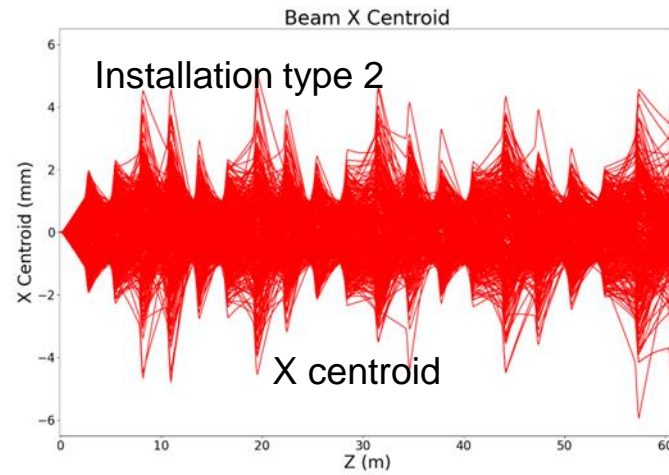
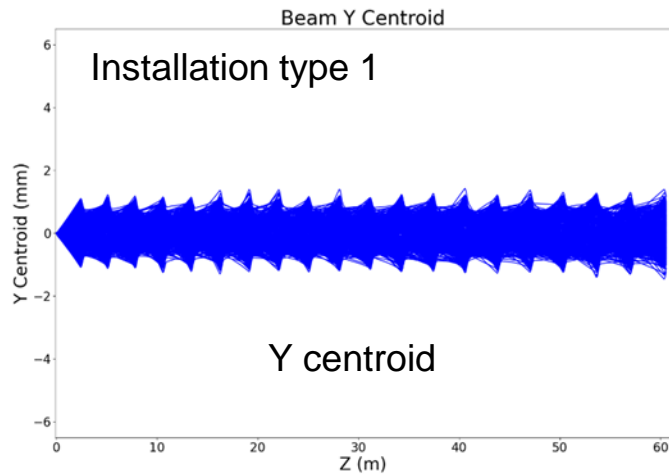


Orbit Correction Simulation Centroid Result 2

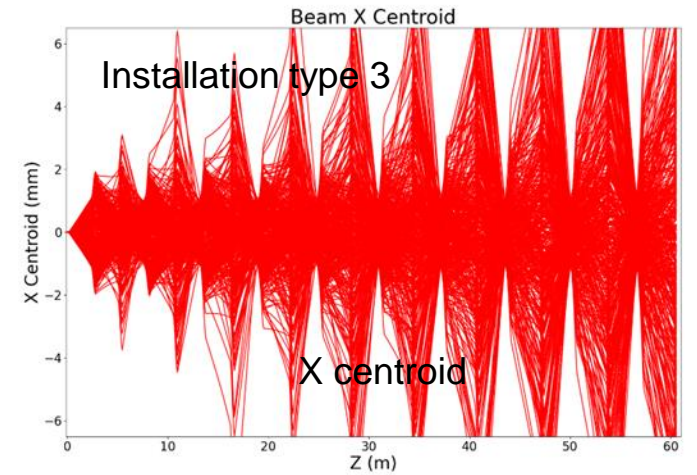
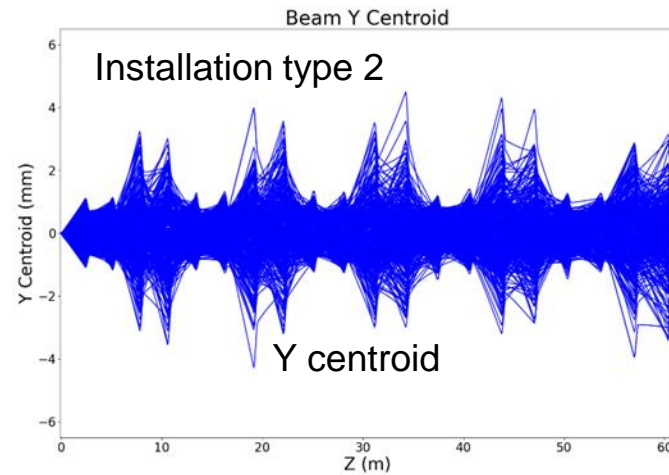
Steer type 2



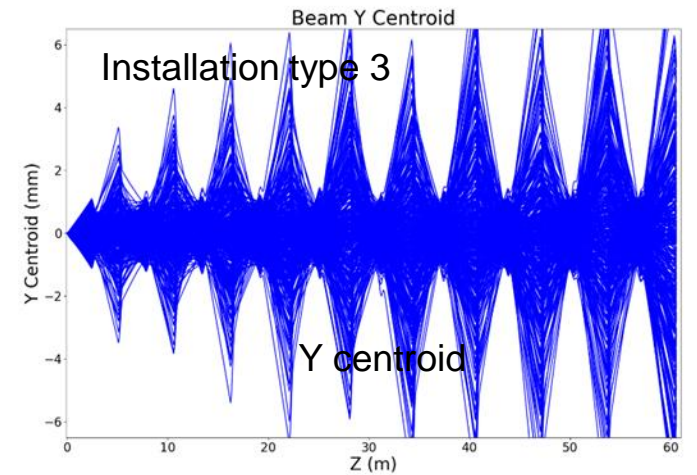
Possible



Possible



Impossible



Orbit Correction Simulation Field Strength

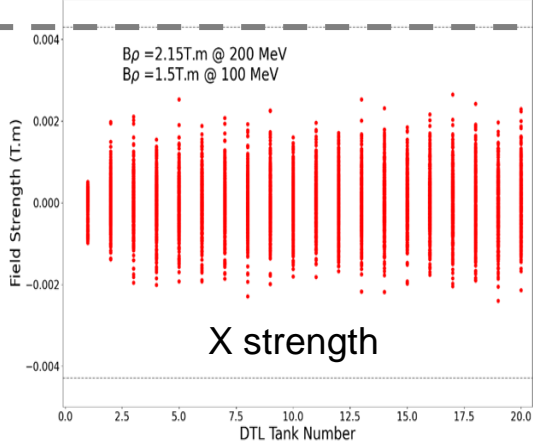
Steer type 1

Reasonable

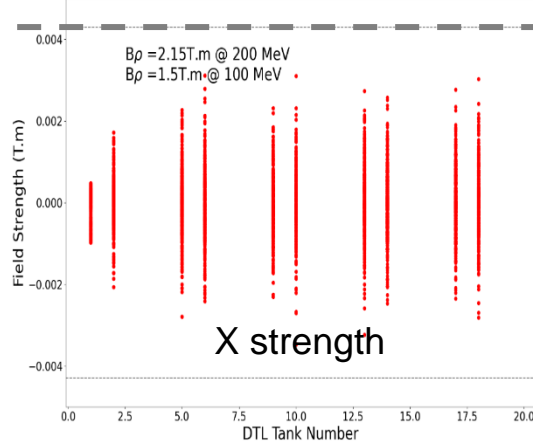
Steer type 2

Criteria

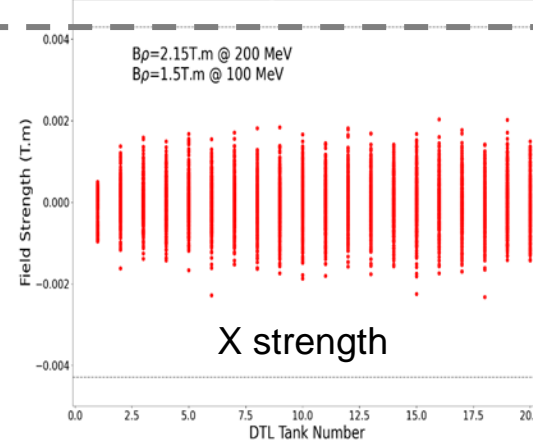
Strength of Steerer X



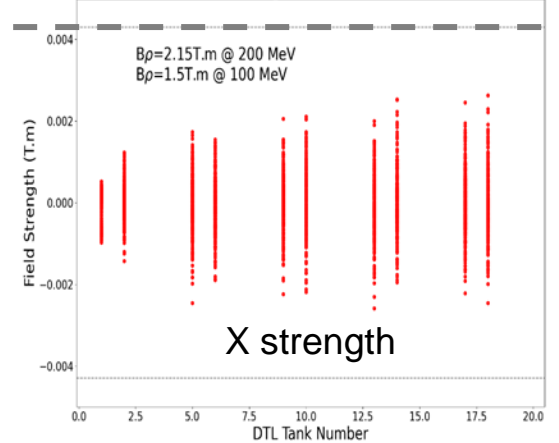
Strength of Steerer X



Strength of Steerer X



Strength of Steerer X



Installation type 1

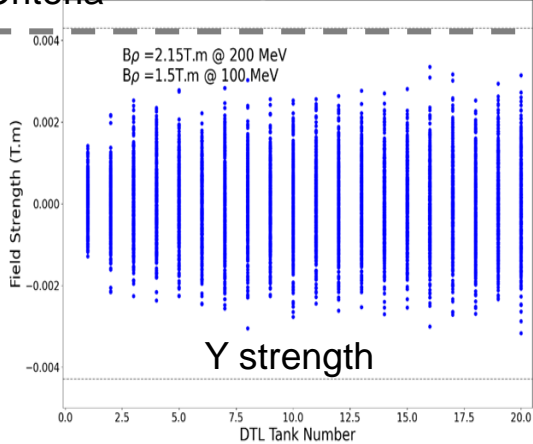
Installation type 2

Installation type 1

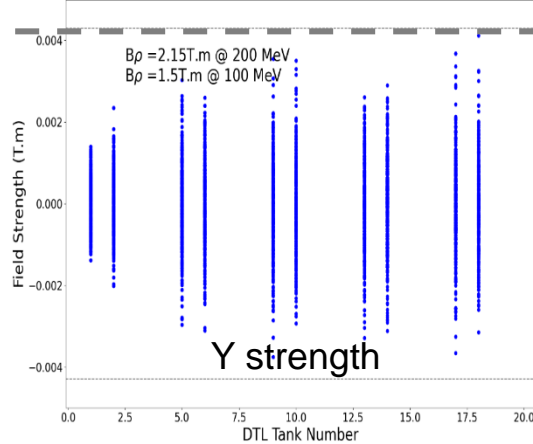
Installation type 2

Criteria

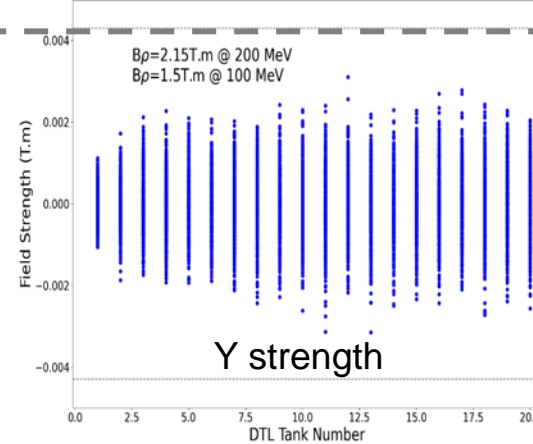
Strength of Steerer Y



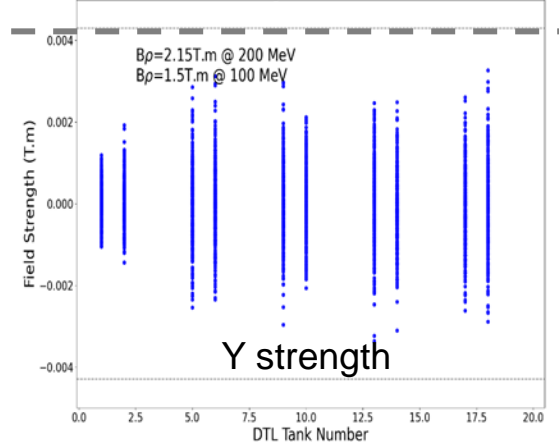
Strength of Steerer Y



Strength of Steerer Y



Strength of Steerer Y



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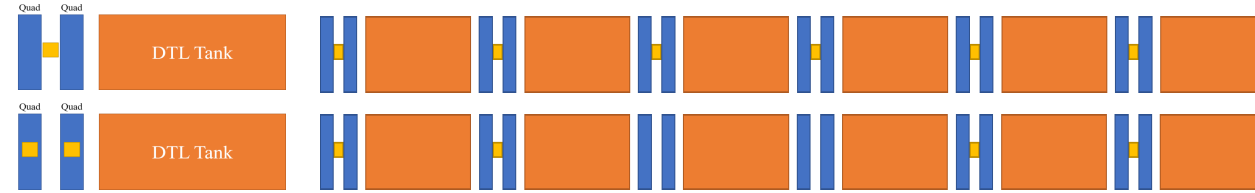
Criteria of Maximum Error & Steering Magnet

Criteria of Maximum Error

Error Type	Value
Quad magnet displacement (dx, dy)	$\pm 150 \mu m$
Quad magnet rotation (ϕ_x, ϕ_y, ϕ_z)	$\pm 0.25^\circ$
Quad magnet gradient	$\pm 1.5\%$
Cavity displacement (dx, dy)	$\pm 150 \mu m$
Cavity rotation (ϕ_x, ϕ_y)	$\pm 0.25^\circ$
Cavity Acc. Voltage	$\pm 1.5\%$
Cavity Phase (ϕ_{sync})	$\pm 1.5^\circ$
Input beam Position (x, y)	$\pm 1 mm$
Input beam angle (x, y)	$\pm 2 mrad$

Suppress Emittance growth below 5%

Criteria of Steering Magnet



[Steer type 1 & 2 + Installation type 1 & 2] are **Possible**

Required maximum field for steering magnet

$$4.3 * 10^{-3} T.m$$

(2 mrad @ 200 MeV)

Summary

- KOMAC start to prepare the energy upgrade up to 200 MeV
- The lattice type is SDTL and the total length is around 70 m
- The designed SDTL lattice is robust for external error (Quad & Cavity)
- Even if there is error, the corrector magnet can adjust it within 2 mrad range

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Thank you

10/24/2024

Input Beam Mismatch

Input beam error (Input beam mismatch)

